#### C-165-100-**13**(1)

# SONY.

# Color Camera Module

**Technical Manual** 



O 2015 Sony Corporation

# **Table of Contents**

Precautions	3
Basic Functions	5
Overview of Functions	5
About the firmware update	
Eclipse	
Spectral Sensitivity Characteristics	
Initial Settings, Custom Preset and Backup	
Mode Condition	
Command List	29
VISCA/RS-232C Commands	
FCB Camera Commands	
Specifications	67
Note on the License	73

# Precautions

#### Software

Use of the demonstration software developed by Sony Corporation or use of the software with customer developed application software may damage hardware, the application program or the camera. Sony Corporation is not liable for any damages under these conditions.

#### Operation

Start the camera control software on your computer after you turn on the camera and the image is displayed.

#### **Operation and storage locations**

Do not shoot images that are extremely bright (e.g., light sources, the sun, etc.) for long periods of time. Do not use or store the camera in the following extreme conditions:

- Extremely hot or cold places (operating temperature -5 °C to +60 °C (23 °F to 140 °F))
- Close to generators of powerful electromagnetic radiation such as radio or TV transmitters
- Where it is subject to fluorescent light reflections
- Where it is subject to unstable (flickering, etc.) lighting conditions
- Where it is subject to strong vibration
- Where it is subject to radiation from laser beams

#### Care of the unit

Remove dust or dirt on the surface of the lens with a blower (commercially available).

#### Other

- Design and specifications are subject to change without notice.
- Do not apply excessive voltage. (Use only the specified voltage.) Otherwise, you may get an electric shock or a fire may occur.
- The CMOS image sensor and IC included in this camera may break if exposed to static electricity. When directly handling this camera, wear an antistatic strap, spread a conductive sheet or similar item under your workbench, and take measures to eliminate static electricity.

• In case of abnormal operation, contact your authorized Sony dealer or the store where you purchased the product.

#### **Handling precautions**

- When handling this unit, be careful not to apply an excessive load to all portions of the unit except for the sheet-metal cover. Otherwise, it may result in a failure.
- This unit is designed to be built in the housing. Therefore, take measures to prevent the unit from receiving the intense light such as sunlight directly from the direction other than the front side. Otherwise, it may cause the image quality degradation.

#### Phenomena specific to CMOS image sensors

The following phenomena that may appear in images are specific to CMOS image sensors. They do not indicate malfunctions.

#### **Rolling shutter**

As CMOS image sensors use shutters that capture images line-by-line, there is a slight time difference between the top and bottom of an image. As a result, images may appear skewed if the camera is moved.

#### White flecks

Although the CMOS image sensors are produced with high-precision technologies, fine white flecks may be generated on the screen in rare cases, caused by cosmic rays, etc.

This is related to the principle of CMOS image sensors and is not a malfunction.

The white flecks especially tend to be seen in the following cases:

- when operating at a high environmental temperature
- when you have raised the master gain (sensitivity)
- when operating in Slow-Shutter mode

#### Aliasing

When fine patterns, stripes, or lines are shot, they may appear jagged or flicker.

#### **Phenomena Specific to Lenses**

#### Ghosting

If a strong light source (e.g., the sun) exists near the incidence angle of the lens, bright spots may appear in the image due to diffuse reflection within the lens.

#### About the trademark

"Exmor R" is trademark of Sony Corporation.

# **Basic Functions**

## **Overview of Functions**

#### In general

#### Power On/Off

Powers the camera on and off. Although the screen is set non-displayed when the power is off, the camera is able to accept the "Power On" VISCA Command.

#### • I/F Clear

Clears the Command buffer of the camera.

#### Address Set

VISCA is a protocol, which normally supports a daisy chain of up to seven connected cameras via RS-232C interface. In such cases, the address set command can be used to assign addresses from 1 to 7 to each of the seven cameras, allowing you to control the seven cameras with the same personal computer. Although the FCB camera does not support direct connection of cameras in a daisy chain, be sure to use the address set command to set the address whenever a camera is connected for the first time.

• ID Write

Sets the camera ID.

• Mute

Blanks the screen and sends out a synchronizing signal.

#### Lens Initialize

Initializes the zoom and focus of the lens. Even when power is turned on, it initializes the zoom and the focus.

#### Zoom

The FCB camera incorporates a 12× optical zoom lens combined with a digital zoom function; this camera allows you to zoom up to 144×.

#### • Optical 12×, f = 3.9 mm to 46.8 mm (F 1.8 to F 2.0)

The horizontal angle of view is approximately 70.7 degrees (wide end) to 6.2 degrees (tele end). Digital Zoom enlarges the center of the subject by expanding each image in both the vertical and horizontal directions. When  $144 \times \text{zoom}$  is used, the number of effective picture elements in each direction reduces to  $^{1}/_{12}$  and the overall resolution deteriorates.

The zoom magnification can be set in the following methods.

#### **Using Standard Mode**

The zoom speed is fixed.

#### Using Variable Mode

There are eight levels of zoom speed.

*In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.* 

#### **Direct Mode**

Setting the zoom position enables quick movement to the designated position.

#### **Digital Zoom**

There are two types of zoom modes; combined mode and separate mode.

#### **Combined Mode**

This is the previously existing zoom method. After the optical zoom has reached its maximum level, the camera switches to Digital Zoom Mode.

#### Separate Mode

In this mode, Optical Zoom and Digital Zoom can be operated separately. You can use digital zoom magnification at any time from within any level of optical magnification. In the combined mode, the digital zoom range can be set. A magnified image with less deterioration can be obtained up to  $1.67 \times$  in QFHD and  $2 \times$  in FHD with the super resolution zoom.

#### About Continuous Zoom Position Reply

With ZoomDirect mode, or when zooming according to a preset, the camera outputs zoom position data when Continues Zoom Position Reply is set to On via a command.

Continues Zoom Position Reply: y0 07 04 69 0p 0p 0q 0q 0q 0q FF

pp: D-Zoom Position qqqq: Zoom Position

#### Focus

Focus has the following modes.

#### • Auto Focus Mode

The minimum focus distance is 10 mm at the optical wide end and 2100 mm at the optical tele end, and is independent of the digital zoom.

The Auto Focus (AF) function automatically adjusts the focus position to maximise the high frequency content of the picture in a center measurement area, taking into consideration the high luminance and strong contrast components.

#### - Normal AF Mode

This is the normal mode for AF operations.

#### - Interval AF Mode

The mode used for AF movements carried out at particular intervals. The time intervals for AF movements and for the timing of the stops can be set in one-second increments using the Set Time Command. The initial setting for both is set to 5 seconds.

#### - Zoom Trigger Mode

When zoom position is changed, it becomes AF mode during the pre-set value (initial setting is set to 5 seconds). Then it stops.

#### • AF Sensitivity

The switching of AF sensitivity can be set.

#### - Normal

Reaches the highest focus speed quickly. Use this when shooting a subject that moves frequently. Usually, this is the most appropriate mode.

#### - Low

Improves the stability of the focus. When the lighting level is low, the AF function does not take effect, even though the brightness varies, contributing to a stable image.

#### Manual Focus Mode

Manual Focus has both a Standard Mode and a Variable Mode. Standard Mode focuses at a fixed rate of speed. Variable Mode has eight speed levels.

*In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.* 

#### One Push Trigger Mode

When a Trigger Command is sent, the lens moves to adjust the focus for the subject. The focus lens then holds that position until the next Trigger Command is input.

#### • Near Limit

Can be set in a range from  $1000 (\infty)$  to E000 (10 mm). Initial setting: B000h (30 cm)

#### Spot focus mode

The spot focus mode allows you to focus on a specific portion of the subject. This mode is used when it is difficult to focus on the subject by using the normal auto focus, and so on. The focusing spot is specified by the area of the entire screen divided into 16-split both vertically and horizontally.

#### White Balance (WB)

White Balance has the following modes.

• Auto

This mode computes the white balance value output using color information from the entire screen. It outputs the proper value using the color temperature radiating from a black subject based on a range of values from 2500K to 7500K.

This mode is the initial setting.

• ATW

Auto Tracing White balance (2000K to 10000K)

- Indoor 3200K Base Mode
- Outdoor 5800K Base Mode

#### • One Push WB

The One Push White Balance mode is a fixed white balance mode that may be automatically readjusted only at the request of the user (One Push Trigger), assuming that a white subject, in correct lighting conditions, and occupying more than 1/2 of the image, is submitted to the camera.

One Push White Balance data is lost when the power is turned off. If the power is turned off, reset One Push White Balance.

#### • Manual WB

This is a mode that enables you to manually set the control of R and B gain up to 256 steps.

#### Outdoor Auto

This is an auto white balance mode specifically for outdoors. It allows you to capture images with natural white balance in the morning and evening.

Sodium Vapor Lamp Auto

This is an auto white balance mode that is compatible with sodium vapor lamps.

Sodium Vapor Lamp

This is a fixed white balance mode specifically for sodium vapor lamps.

Sodium Vapor Lamp Outdoor Auto

This is an auto white balance mode specifically for outdoors, which is compatible with sodium vapor lamps.

#### Note

High-pressure sodium lamps are supported. Proper white balance may not be captured for some subjects when using low-pressure sodium lamps.

#### Auto Exposure Mode (AE)

A variety of AE functions are available for optimal output of subjects in lighting conditions that range from low to high.

#### • Full Auto

Iris, Gain and Shutter Speed can be set automatically.

#### • Shutter Priority<sup>1)</sup>

Adjust with Variable Shutter Speed (1/1 to 1/10,000 sec., 16 high-speed shutter speeds plus 6 low-speed shutter speeds), Auto Iris and Gain.

1) Flicker in the East Japan area (50 Hz power supply frequency) can be eliminated by setting shutter to 1/100s.

#### • Iris Priority

Adjust with Variable Iris (F1.8 to Close, 14 steps), Auto Gain and Shutter speed

• Manual

Adjust with Variable Shutter speed, Iris and Gain

#### • Bright

Adjust with Variable Iris and Gain (Close to F1.8, 14 steps and F1.8 at 15 steps)

#### AE – Shutter Priority

The shutter speed can be set freely by the user to a total of 22 steps – 16 high speeds and 6 low speeds. When the slow shutter is set, the speed can be adjusted according to subject brightness. The picture output is read at a normal rate from the memory. The memory is updated at a low rate from the CMOS. AF following capability is lowered and also the number of frame to be displayed is decreased.

In high speed mode, the shutter speed can be set up to 1/10,000s. The iris and gain are set automatically, according to the brightness of the subject.

Data	59.94/29.97 mode	50/25 mode
15	1/10000	1/10000
14	1/6000	1/6000
13	1/4000	1/3500
12	1/3000	1/2500
11	1/2000	1/1750
10	1/1500	1/1250
0F	1/1000	1/1000
0E	1/725	1/600
0D	1/500	1/425
0C	1/350	1/300
0B	1/250	1/215
0A	1/180	1/150
09	1/125	1/120
08	1/100	1/100
07	1/90	1/75
06	1/60	1/50
05	1/30	1/25
04	1/15	1/12
03	1/8	1/6
02	1/4	1/3
01	1/2	1/2
00	1/1	1/1

#### AE – Iris Priority

The iris can be set freely by the user to 14 steps between F1.8 and Close.

The gain and shutter speed are set automatically, according to the brightness of the subject.

Data	Setting value	Data	Setting value
11	F1.8	0A	F5.6
10	F2	09	F6.8
0F	F2.4	08	F8
0E	F2.8	07	F9.6
0D	F3.4	06	F11
0C	F4	05	F14
0B	F4.8	00	CLOSE

#### AE – Manual

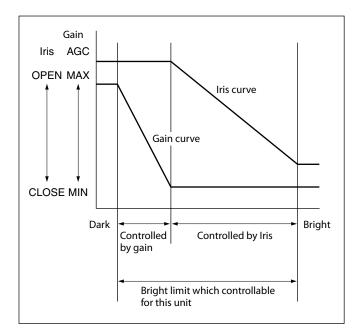
The shutter speed (22 steps), iris (14 steps) and gain (16 steps) can be set freely by the user.

#### AE – Bright

The bright control function adjusts both gain and iris using an internal algorithm, according to a brightness level freely set by the user. Exposure is controlled by gain when dark, and by iris when bright. As both gain and iris are fixed, this mode is used when exposing at a fixed camera sensitivity. When switching from Full Auto or Shutter Priority Mode to Bright

Mode, the current status will be retained for a short period of time. Only when the AE mode is set to "Full Auto" or

"Shutter Priority," can you switch it to "Bright."



Data	Iris	Gain	Data	Iris	Gain
20	F1.8	45 dB	11	F1.8	0 dB
1F	F1.8	42 dB	10	F2	0 dB
1E	F1.8	39 dB	0F	F2.4	0 dB
1D	F1.8	36 dB	0E	F2.8	0 dB
1C	F1.8	33 dB	0D	F3.4	0 dB
1B	F1.8	30 dB	0C	F4	0 dB
1A	F1.8	27 dB	0B	F4.8	0 dB
19	F1.8	24 dB	0A	F5.6	0 dB
18	F1.8	21 dB	09	F6.8	0 dB
17	F1.8	18 dB	08	F8	0 dB
16	F1.8	15 dB	07	F9.6	0 dB
15	F1.8	12 dB	06	F11	0 dB
14	F1.8	9 dB	05	F14	0 dB
13	F1.8	6 dB	00	CLOSE	0 dB
12	F1.8	3 dB			

When switching from the Shutter Priority mode to the Bright mode, the shutter speed set in the Shutter Priority mode is maintained.

#### **Gain Limit Setting**

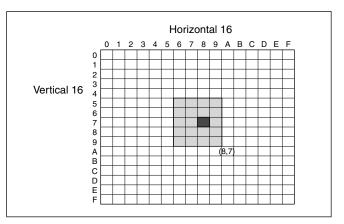
The gain limit can be set at the Full Auto, Shutter Priority and Iris Priority of the Auto Exposure Mode. Use this setting when you want to obtain image in which signal-to-noise ratio is particularly important.

#### **Gain Point Setting**

Set the Gain Point in the middle between 0dB and gain limit. The shutter speed can be changed from the point when the set gain value is reached. When you want to obtain the motion-priority image, use this setting.

#### **Spot Exposure Mode**

In Full Auto AE, the level for the entire screen is computed and the optimum level of Iris, Gain, etc. are determined. In Spot AE, a particular section of the subject can be designated, and then that portion of the image can be weighted and a value computed so that Iris, Gain, etc. can be optimized to obtain an image. For example, in an image with a lot of movement and with varying levels of brightness, portions without much change can be designated as such a "spot," and changes to the screen can be minimized in that area. As shown in the diagram below, a range of 16 blocks vertically and 16 blocks horizontally can be designated. The level is calculated by the value of the surrounding blocks (shaded) including the designated center block (black). The range of the Spot AE frame is fixed to 5 blocks vertically and 4 blocks horizontally.



#### **Exposure Compensation**

Exposure compensation is a function which offsets the internal reference brightness level used in the AE mode, by steps of 1.5 dB.

Data	Step	Setting value
0E	+7	+10.5 dB
0D	+6	+9 dB
0C	+5	+7.5 dB
0B	+4	+6 dB
0A	+3	+4.5 dB
09	+2	+3 dB
08	+1	+1.5 dB
07	0	0 dB
06	-1	-1.5 dB
05	-2	-3 dB
04	-3	-4.5 dB
03	-4	-6 dB
02	-5	-7.5 dB
01	-6	-9 dB
00	-7	-10.5 dB

#### Slow AE (Auto Exposure)

The slow AE Response function allows you to reduce the exposure response speed. Usually the camera is set up so that the optimum exposure can be obtained automatically within about 1 second. However, using the slow AE response function allows you to lengthen the auto exposure response speed from the initial setup speed (01h) to approx. 10 minutes (30h) (at normal shutter speed).

For example, with the normal setting (about 1 second), if the headlights of a car are caught by the camera, the camera automatically adjusts the exposure so that it can shoot a high-intensity subject (in this case, the headlights). As a result, images around the headlights, that is, the rest of the subject, except the headlights, becomes relatively dark, and poorly distinguished. However, using the slow AE function means the AE response speed will be slower, and response time will be longer. As a result, even if the camera catches a highintensity subject (e.g., the headlights) for a moment, you can still easily distinguish the portions of the image surrounding the headlights.

#### **High Resolution Mode**

This mode enhances edges and produces higher definition images.

#### **Aperture Control**

Aperture control is a function which adjusts the edge enhancement of objects in the picture.

When it is set to Auto, the adjustment is performed automatically.

When it is set to Manual, you can adjust multiple setting items. Sometimes, the noise particle that is generated when the gain is increased becomes noticeable because its edge is enhanced by this function. In this case, lower the edge enhancement level or adjust the edge enhancement amount of noise by "Crispening".

#### **Backlight Compensation**

When the background of the subject is too bright, or when the subject is too dark due to shooting in the AE mode, back light compensation will make the subject appear clearer.

#### Visibility Enhancer (VE)

Depending on the imaging scene, the Visibility Enhancer function makes the darker part of a camera image brighter, and automatically correct brightness and contrast to show bright parts clearly.

#### **Defog mode**

When the surrounding area of the subject is foggy and low contrast, the defog mode will make the subject appear clearer.

This function has four steps: OFF, Low, Mid and High

#### Low delay mode

The low delay mode is a function to reduce the amount of delay between the image sensor output and the image output.

During the low delay mode, the following functions cannot be used due to the HW constraint.

- Digital zoom
- Distortion correction
- Image Stabilizer
- StableZoom

During the low delay mode, the angle of view is shifted to the Tele side in the 720 output mode due to the HW constraint.

#### **Highlight Compensation (HLC)**

HLC (highlight correction) is a function to adjust AE and AF, and to perform the masking of light area as required when a high intensity spot light is detected. It allows you to easily read the number of vehicles and number plate in the indoor parking area or in the outdoor during the night.

#### **Maximum Shutter Limit**

When the subject becomes bright, the shutter speed becomes high. This is a function to put an upper limit on the shutter speed. When you shoot a bright subject, it reduces the image roughness and a smooth motion image can be obtained.

#### **Minimum Shutter Limit**

When the subject becomes dark, the shutter speed becomes slow, and then the gain is increased. This is a function to put a lower limit on the shutter speed. It prevents the camera shake when you shoot a moving subject in a dark place.

#### Noise Reduction (NR)

The NR function removes noise (both random and non-random) to provide clearer images. This function has six steps: levels 1 to 5, plus off. The NR effect is applied in levels based on the gain, and this setting value determines the limit of the effect. In bright conditions, changing the NR level will not have an effect.

When it is set to level 7Fh, you can set NR of 2D/3D individually.

#### **High Sensitivity Mode**

In this mode, the maximum gain increases, enabling to obtain a brighter output even in a darker environment. However, if the gain reaches high level, the image will have a large amount of noise.

#### Variable Gamma Mode

There are standard (01h) mode and straight gamma (02h) mode.

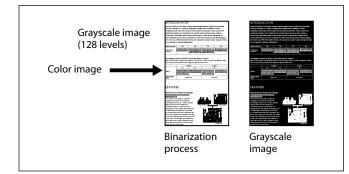
Also, you can select the mode from 512 patterns.

#### **Gamma Offset**

You can set within the range of -64 to +64 in each mode of variable gamma mode.

#### **Color Enhancement**

The shot color image can be output in two colors in the grayscale image based on the density level (brighter or darker than the threshold value) of the image portion. (The threshold level can be set with an optional level.)



#### Note

Flicker on images with color enhancement is not a malfunction of the camera. Flicker can be reduced by setting the threshold level and the aperture control.

#### **Temperature Reading Function**

The conversion value (hex) of the temperature sensor built into to the camera can be read by using a query command. The conversion value has an error of  $\pm 3$  C, and because the temperature sensor is inside the camera, this value is not the ambient temperature. Use it as a reference value.

#### **Slow Shutter On/Off**

When set to "On," the slow shutter functions automatically when the light darkens. This setting is available only when the AE mode is set to "Full Auto." The initial setting is "Slow Shutter Off."

#### Low-Illumination Chroma Suppress Mode

You can configure a chroma suppress mode for lowillumination conditions. This can be useful when color noise is particularly noticeable in such conditions. Four levels (disabled and three levels) are available for the low-illumination chroma suppress mode.

#### ICR (IR Cut-Removable) Mode

The IR Cut-Filter installed in front of the image sensor can be engaged or disengaged by the mechanical structure. The sensitivity in the infrared region is increased by disengaging the IR Cut-Filter, allowing the camera to capture the image in darker places. When the auto ICR mode is set to On, the image becomes black and white.

#### **Custom Color Gain**

You can configure the color gain. Use this setting when bright color is particularly important. The initial setting 100% (4h) can be set to range from approx. 60% (0h) to 200% (Eh) with 15 stages.

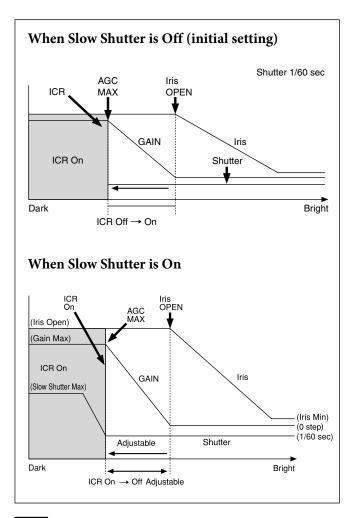
#### **Custom Color Phase**

You can configure the color phase. The initial setting 0 degrees (7h) is adjustable between approx. –14 degrees (0h) to +14 degrees (Eh), in 15 increments.

#### Auto ICR Mode

Auto ICR Mode automatically switches the settings needed for attaching or removing the IR Cut Filter. With a set level of darkness, the IR Cut Filter is automatically disabled (ICR On), and the infrared sensitivity is increased. With a set level of brightness, the IR Cut Filter is automatically enabled (ICR Off). Also, on systems equipped with an IR light, the internal data of the camera is used to make the proper decisions to avoid malfunctions.

Auto ICR Mode operates with the AE Full Auto setting.



#### Note

Depending on the information such as brightness, etc., in the On/ Off settings condition, a malfunction may occur when the subjects largely consisting of blue and green colors are taken.

#### Camera ID

The ID can be set up to 65,536 (0000h to FFFFh). As this will be memorized in the nonvolatile memory inside, data will be saved.

#### **Picture Effect**

It consists of the following function. • Black & White: Monochrome Image

#### Image stabilizer

When the image stabilizer function is set to On, you can obtain the image with less screen blur caused by shaking and so on. The correction effect can be achieved at the vibration frequency around 10 Hz. The image stabilizer function uses the digital zoom method. Although there are changes in the angle of view and resolution, the sensitivity is maintained.

#### Note

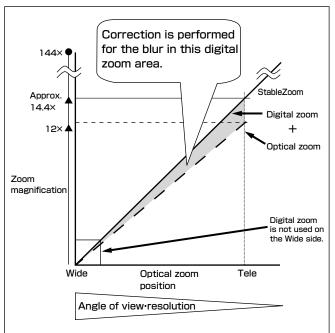
The image stabilizer function may not work under the environment

of high frequency vibration components. When using the camera under such environment, set the image stabilizer function to Off.

#### "StableZoom"

"StableZoom" is a function to perform correction using the image stabilizer function according to the zoom magnification and zoom the image up to approx. 14.4× smoothly by combining the optical zoom with the digital zoom. By zooming the image furthermore using the digital zoom, the image is zoomed up to 144×. On the Wide side, the image without the deterioration in resolution can be obtained because the digital zoom is not used. On the other hand, the correction effect by the image stabilizer function is maximized on the Tele side, reducing the blur.

"StableZoom" can be set to On/Off by the register setting.



Actually, approx. 1.03x zoom is used at the Wide end.

#### Others

#### E-FLIP

This function reverses the video output from the camera vertically and horizontally.

#### **LR Reverse**

This function reverses the video output from the camera horizontally.

#### Freeze

This function captures an image in the field memory of the camera so that this image can be output continuously.

Because communication inside the camera is based on V cycle, the captured image is always the one 3V to 4Vs after the sending of a Command. Thus, you can not specify a time period after sending EVEN, ODD or a Command.

#### **Memory (Position preset)**

Using the position preset function, 16 sets of camera shooting conditions can be stored and recalled. This function allows you to achieve the desired status instantly, even without adjusting the following items each time.

- Zoom Position
- Digital Zoom On/Off/Super Resolution Zoom
- Focus Auto/Manual
- Focus Position
- AE Mode
- Shutter control parameters
- Bright Control
- Iris control parameters
- Gain control parameters
- Exposure Compensation On/Off
- Exposure Level
- Backlight Compensation On/Off
- Slow Shutter On/Off
- White Balance
- R/B Gain
- Aperture Control
- ICR On/Off
- Defog

#### **Custom Preset**

As with the position preset function, the camera shooting conditions can be stored and recalled. The settings are recalled when the power is turned on. *For setting items, see the "Initial Settings, Custom Preset and Backup" section on page 24.* 

#### **User Memory Area**

A user area of 16 bytes allows you to write data, such as an ID for each customer, data for each system, and so on, freely.

#### Note

Rewriting of memory is not unlimited. Be careful to avoid using the memory area for such as unnecessary tasks as rewriting the contents of the memory for every operation.

#### **Register Setting**

The camera's initial settings can be changed by the register setting command. Register Setting Command:

8x 01 04 24 mm 0p 0q FF

mm: Register No. (=00 to 7F) pq: Register Value (=00 to FF) Register Inquiry Command: 8x 09 04 24 mm FF mm: Register No. y0 50 0p 0p FF pp: Register Value (returned from the camera)

The register setting items and No. are as follows. For details, see "Register Setting" on page 54, 55. Baud Rate: 00 Communication speed can be changed. Digital Output: 60 The color space can be set. Monitoring Mode: 72 The Digital output mode can be configured. Low Delay Mode: 75 ON/OFF can be set. (initial setting is OFF.) Zoom Limit: 50 (Wide end), 51 (Tele end) The Wide and Tele zoom limits can be set. D-Zoom Max: 52 The maximum digital zoom limit can be set (initial settinig is  $12 \times$ ). FocusTrace: 54 When you want to prioritize zoom speed, set FocusTrace to Off to minimize the transition time between Wide and Tele zoom (although the image may be blurred because focus is not tracked). FocusOffset: 55 Placing a dome cover in front of the camera may cause the focal distance of the camera to change. Especially at the Tele end, this effect exceeds the AF range, so focus cannot track, although it responds to changes in this value. For details, see "Register Setting" on page 55. Extended mode: 5F ON/OFF can be set. (initial setting is OFF.) For details, see page 18.

#### Note

After changing the register setting, turn off the camera, then turn it on again.

#### **Privacy Zone Masking Settings**

For details, see page 14.

#### **Motion detection**

For details, see page 16.

#### **Title Display**

- You can set a title of up to 11 lines. One line can contain up to 20 characters.
- You can set display on/off, the horizontal position of the first character, blinking state and color for each line.
- The camera gives priority to a title display when the camera status is displayed on the relevant line. On the lines where a title is not set, the camera status is displayed.

Line Number				00h to 0Ah			
ri-posit	H-position 00h to 1Fh 00h WHIT				TF		
			01h			YELLOW	
				02h		VIOI	
Color				03h		RE	
				04h		CYA	N
				05h		GRE	EN
				06h		BLU	
Blink				00h		Of	
				01h		Or	1
00	01	02	03	04	05	06	07
А	В	С	D	Е	F	G	Η
08	09	0A	0B	0C	0D	0E	0F
Ι	J	Κ	L	М	N	0	Р
10	11	12	13	14	15	16	17
Q	R	S	Т	U	V	W	Х
18	19	1A	1B	1C	1D	1E	1F
Y	Ζ	&		?	!	1	2
20	21	22	23	24	25	26	27
3	4	5	6	7	8	9	0
28	29	2A	2B	2C	2D	2E	2F
À	È	Ì	Ò	Ù	Á	É	Í
30	31	32	33	34	35	36	37
Ó	Ú	Â	Ê	Ô	Æ		Ã
38	39	3A	3B	3C	3D	3E	3F
Õ	Ñ	Ç	ß	Ä	Ï	Ö	Ü
40	41	42	43	44	45	46	47
Å	\$		¥		£	ś	i
48	49	4A	4B	4C	4D	4E	4F
ø	"	:	,		,	/	-
50	51	52	53	54	55	56	57
#	%	(	)	*	+	;	<
58	59	5A	5B	5C	5D	5E	5F
=	>	@	[	١	]	٨	_
60	61	62	63	64	65	66	67
ć	а	b	с	d	e	f	g
68	69	6A	6B	6C	6D	6E	6F
h	i	j	k	1	m	n	0
70	71	72	73	74	75	76	77
р	q	r	s	t	u	v	w
78	79	7A	7B	7C	7D	7E	7F
x	y	Z	{	-	}	~	

"36", "42", "44" and "7F" are the reserved areas. When you enter the space, use 1B.

## **Privacy Zone Masking Function**

Privacy Zone masking protects private objects and areas such as house windows, entrances, and exits which are within the camera's range of vision but not subject to surveillance.

Privacy zone masking can be masked on the monitor to protect privacy.

#### Features

- Mask can be set on up to 48 places according to Pan/ Tilt positions.
- Mask can be displayed on 24 places per screen simultaneously.
- Individual on/off zone masking settings.
- Two colors can be individually set for each of 48 privacy zones.
- Interlocking control with zooming.
- Interlocking control with Pan/Tilt.
- Non-interlocking control with Pan/Tilt.

#### **Details of Setting Commands**

#### Set Mask

**Command:** 8x 01 04 76 mm nn 0r 0r 0s 0s FF

Para	Parameters:		
mm	Setting Mask		
	See "mm: Mask setting list" in "Parameters" on page 15.		
nn	Selects new setting or resetting for the zone. See "nn:		
	Setting" in "Parameters" on page 15.		
rr	Sets the half value "w" of the Mask Width.		
ss	Sets the half value "h" of the Mask Height.		
	See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.		

**Comments:** To set the mask, first display the object at the center of the screen. When "nn" is set to 1, the current Pan/Tilt/Zoom Position is recorded in internal memory.

When "nn" is set to 0, the Pan/Tilt/Zoom Position in memory is not changed.

#### Notes

- The tilt angle at which you can set the mask is between -70 to +70 degrees.
- It is recommended that you set the size to at least twice the size of the object (height and width).

#### Set Display

**Command:** 8x 01 04 77 pp pp pp FF **Parameter:** 

рр рр рр рр	Each 24 Privacy Zones corresponds to the BIT.
	See "pp pp pp pp: Mask bit" in "Parameters" on
	page 16.

**Comments:** Each of 24 Privacy zones can be switched on and off individually by a single VISCA Command. If you want to display a Privacy zone, you must set its bit to 1. If you do not want to display a Privacy zone, you must set its bit to 0.

#### Set Mask Color

**Command:** 8x 01 04 78 pp pp pp pp qq rr FF **Parameter:** 

рр рр рр рр	Each 24 Privacy Zones correspond to the BIT. See "pp pp pp pp: Mask bit" in "Parameters" on
99	page 16. Set the color code
rr	Set the color code. See "qq, rr: Color code" in "Parameters" on page 16.

**Comments:** Two different color masks can be chosen. Two colors can be individually set for each of 24 privacy zones.

If the bit of parameter (pp pp pp pp) is set to "0", mask color will be "qq" color (Color code). If the bit of parameter (pp pp pp pp) is set to "1", the mask color will be "rr" color (Color code). **Example:** 8x 01 04 78 00 00 00 03 00 07 FF The mask color of Mask\_A and Mask\_B is White (color code 07h), and the mask color of the other Mask (C to X) is Black (color code 00h).

#### Set Pan Tilt Angle

**Command:** 8x 01 04 79 0p 0p 0p 0q 0q 0q FF **Parameter:** 

ррр	Pan Angle
qqq	Tilt Angle See "Setting pan/tilt angle" in "Parameters" on page 16.

**Comments:** Pan/Tilt angle settings are hexadecimal data.

The resolution of Pan/Tilt angle is 0.088 degrees.

#### Notes

- When you set the pan/tilt angle, locate the pan/tilt position at the center point of the FCB camera's position.
- If you set the pan/tilt angle or zoom the camera, a bigger mask will be displayed for about one second.

#### Set PTZ Mask

**Command:** 8x 01 04 7B mm 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r FF

#### Parameter:

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 15.
ppp	Pan Angle (000 to FFF)
	See "Setting pan/tilt angle" in "Parameters" on page 16.
qqq	Tilt Angle (000 to FFF)
	See "Setting pan/tilt angle" in "Parameters" on page 16.
rrrr	Zoom Position (000 to 4000)
	See "Zoom Ratio and Zoom Position (for reference)" on
	page 52.

**Comments:** Mask can be set at the desired position by setting the pan tilt angle and zoom position using this command. The set value can be input by hexadecimal number.

#### Note

Privacy mask zone follows the change of angle of view according to zoom. However, the follow might be delayed for a moment if there is any big change, such as when using D-Zoom or E-FLIP.

#### Non Interlock Mask

**Command:** 8x 01 04 6F mm 0p 0p 0q 0q 0r 0r 0s 0s FF

#### **Parameters:**

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 15.
рр	Sets the center position "x" of the Mask on screen.
qq	Sets the center position "y" of the Mask on screen.
rr	Sets the half value "w" of the Mask Width.
SS	Sets the half value "h" of the Mask Height.
	See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.

**Commands:** Mask does not interlock with pan/tilt. The limitations of parameters are as follows. (hexadecimal representation)

x: ±50h

w: ±50h

y: ±2Dh

h: ±2Dh

#### Note

When the Set Mask command and the Non Interlock Mask command are set to the same mask, the command set later becomes effective.

#### Parameters

#### mm: Mask setting list

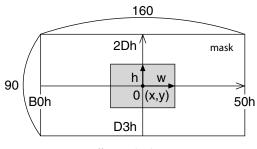
Mask Name	mm (Hex)
Mask_A	00h
Mask_B	01h
Mask_C	02h
Mask_D	03h
Mask_E	04h
Mask_F	05h
Mask_G	06h
Mask_H	07h
Mask_I	08h
Mask_J	09h
Mask_K	0Ah
Mask_L	0Bh
Mask_F Mask_G Mask_H Mask_I Mask_J Mask_K	05h 06h 07h 08h 09h 0Ah

Mask Name	mm (Hex)
Mask_M	0Ch
Mask_N	0Dh
Mask_O	0Eh
Mask_P	0Fh
Mask_Q	10h
Mask_R	11h
Mask_S	12h
Mask_T	13h
Mask_U	14h
Mask_V	15h
Mask_W	16h
Mask_X	17h

#### nn:Setting

nn	Setting
00	Resetting the zone size (the value of w,h) for the existing mask.
01	Setting newly the zone size (the value of w,h).

#### pp: x, qq: y, rr: w, ss: h



Effective display area

#### Note

The priority order of the mask display is in the sequence from A (highest) to X (lowest).

When you set the parameters of masks non-sequentially, it is recommended that you set the mask whose priority order is higher, first.

#### pp pp pp pp: Mask bit

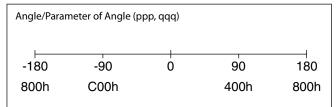
	pp								pp							
bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Mask	-	-	Х	W	V	U	Т	S	-	-	R	Q	Р	0	Ν	М
	nn								nn							
bit	рр 7	6	5	4	3	2	1	0	рр 7	6	5	4	3	2	1	0

The "-" must be "0".

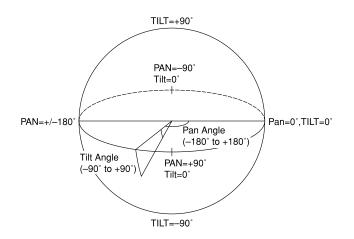
#### qq, rr: Color code

Mask (color)	Code (qq, rr)	Translucence (qq, rr)
Black	00 h	10 h
Gray1	01 h	11 h
Gray2	02 h	12 h
Gray3	03 h	13 h
Gray4	04 h	14 h
Gray5	05 h	15 h
Gray6	06 h	16 h
White	07 h	17 h
Red	08 h	18 h
Green	09 h	19 h
Blue	0A h	1A h
Cyan	0B h	1B h
Yellow	0C h	1C h
Magenta	0D h	1D h
Mosaic		7F h

#### Setting pan/tilt angle



Set the angle resolution to 360 (degree)/4096 (1000h).



### **Motion Detection (MD) Function**

This function instructs the camera to detect movement within the monitoring area and then send an alarm signal automatically. The Detect signal goes out through the VISCA

Command.

#### Features

- You can set a frame for the detection range of 16 (horizontally) × 8 (vertically) blocks.
- You can set up to four frames.
- When the motion is detected in the set frame, the Alarm Replay VISCA Command is sent.
- The threshold level for detection can be set (common to four frames).
- The interval of alarm detection can be set up to 255 seconds in units of one second.
- You can set on/off for each frame.
- The frame number is also sent with Alarm Replay to report in which frame the motion has been detected.

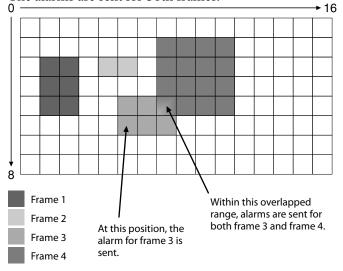
#### Frames

#### **Setting frames**

You can set the frame by assigning the starting point and terminating point vertically and horizontally. You can set up to four frames.

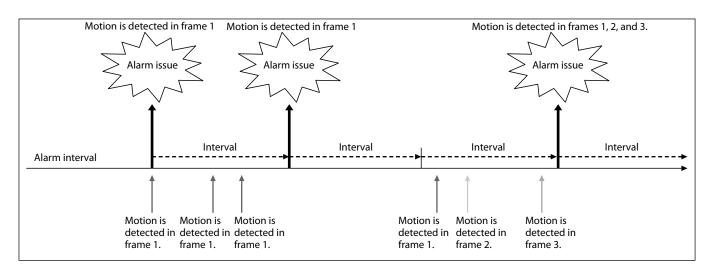
# When motion is detected within the range where frames overlap

The alarms are sent for both frames.



#### **Sending Alarms**

- When motion is detected, the Alarm Replay command is issued via the serial command (VISCA) communication line.
- When motion is detected within the set interval, the alarm is issued after the interval time elapsed.



#### **Setting Commands**

#### • MD On/Off

The Display mode is selected by the Function Set command and frames are set by the Frame Set command. By sending an MD On command, the frame is displayed when motion is detected in the set frame. The Alarm Reply command is sent via the serial command (VISCA) communication line.

8x 01 04 1B 02 FF --- On 8x 01 04 1B 03 FF --- Off

#### • Function Set

Select the detected frame, and set the Threshold Level and the Interval Time.

8x 01 04 1C 0m 0n 0p 0q 0r 0s FF

- m: Display Mode on/off (bit0)
- n: Detection Frame set on/off (bit0:Frame0, bit1: Frame1, bit2:Frame2, bit3:Frame3)

	(0 to F)
pq: Threshold	(00 to FF)
rs: Interval time set	(00 to FF)

(When pq and rs are 0, the command is received, but the setting is disabled.)

#### • Frame Set

You can set up to four frames by assigning the starting and terminating points.

#### Note

Set a terminating point higher vertically and horizontally than the starting point. If you set the wrong value, an error occurs.

8x 01 04 1D 0m 0p 0q rr 0s FF

- m: Select Detection Frame (0: Frame0, 1: Frame1, 2: Frame2, 3: Frame3) -- (0, 1, 2, 3)
- p: Frame set Start Horizontal Position -- (00 to 0F)
- q: Frame set Start Vertical Position -- (00 to 07)
- r: Frame set End Horizontal Position -- (01 to 10)
- s: Frame set End Vertical Position -- (01 to 08)

#### Alarm Reply

When motion is detected in the set frame, the camera issues this command. This command includes the information on the number of the detected frame.

#### y0 07 04 1B 0p FF

p: Frame Number (bit0: Frame0, bit1: Frame1, bit2: Frame2, bit3: Frame3)

#### **Extended Commands**

Extended commands support the following functions (described previously).

Turn on this mode (for details, see "Extended Mode" in "Register Setting" on page 55) to enable the following functions.

#### • Exposure Compensation

The setting can be set in steps of approximately 0.2dB (-128 (00h) to approximately +127 (FFh)).

#### *For details, see page 8.* • Aperture Control

The setting can be set to 256 levels (00h to FFh). For details, see page 9.

#### • Custom Color Gain

The initial setting is 100% (80h), and the setting can be set to 256 levels from approximately 0% (00h) to approximately 200% (FFh).

For details, see page 10.

#### Custom Color Phase

The initial setting is 0 degrees (80h), and the setting can be set to 256 levels from approximately -14 degrees (00h) to approximately +14 degrees (FFh).

For details, see page 10.

#### • Auto ICR Mode

The setting of ICR ON→OFF threshold can be set when Auto ICR is on.

The setting range is 00h to FFh.

The setting of ICR OFF $\rightarrow$ ON threshold (On Level) can be set when Auto ICR is on.

can be set when Auto ICR is on.

The setting range is 00h to 16h. *For details, see page 10.* 

### Note

When the extended mode is Off, CMD\_NOT\_EXEC will be returned if you send the extended commands to the camera. When the extended mode is On, CMD\_NOT\_EXEC will be returned if you send the normal commands to the camera.

# About the firmware update

#### Overview

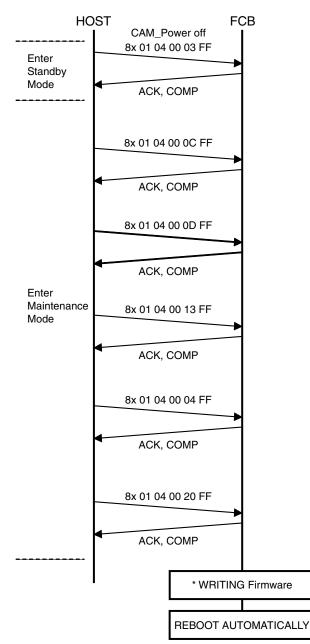
This document descries detailed operation for firmware update.

#### Serial Port Setting during maintenance mode

Communication Speed	115200 bps
Data bit	8 bit
Parity	None
Stop bit	1 bit
Flow control	None

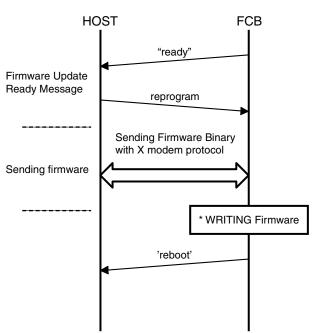
#### Update Procedure (UART)

Enter Maintenance Mode

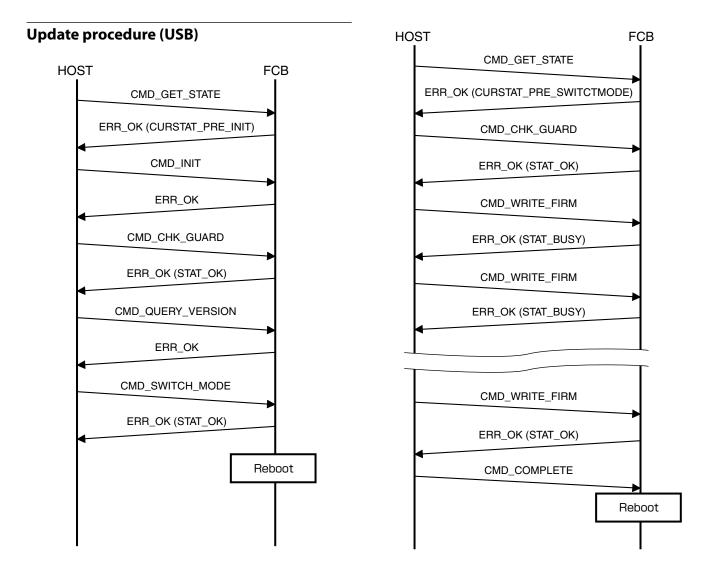


\* When power is off during this period, camera will be broken.

#### Maintenance Mode

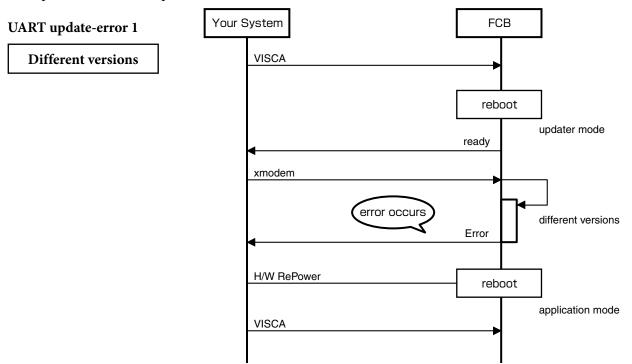


\* When power is off during this period, camera will be broken.



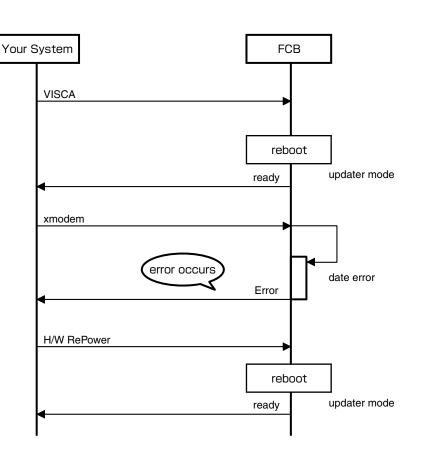
#### **Error occurrence patterns**

The update (UART) error patterns are as follows.



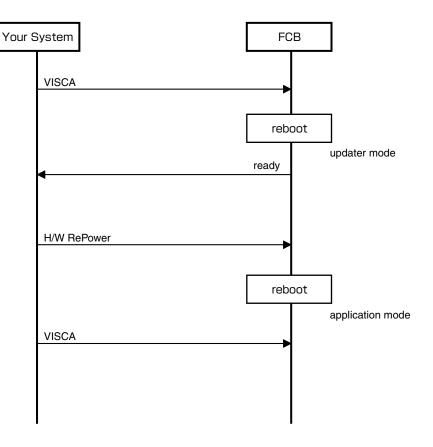
#### UART update-error 2

Error during update

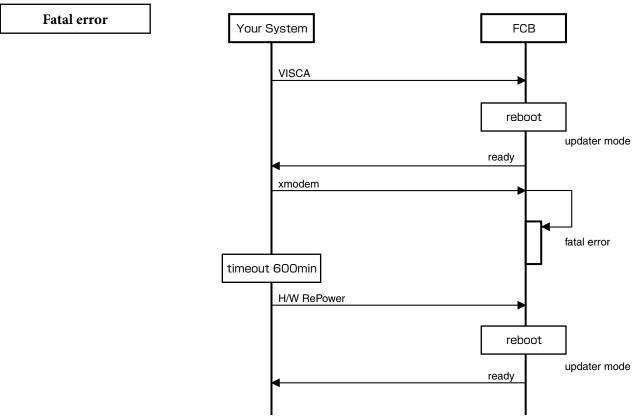


#### UART update-error 3

No update

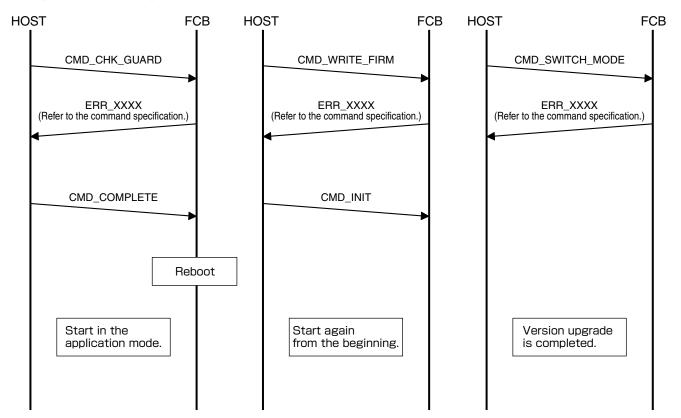


#### UART update-error 4



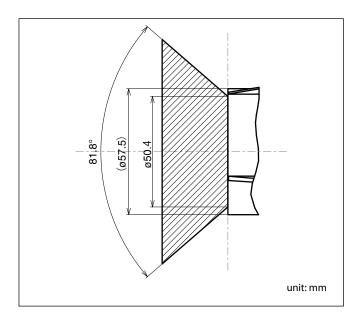
#### **Abnormal USB**

The update (USB) error patterns are as follows.

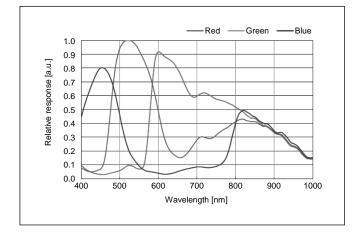


# Eclipse

When designing the housing, refer to the dimensional allowance as shown in the figure below.



# Spectral Sensitivity Characteristics



Use the graph as a reference value. (We can not guarantee these values.)

This data is measured when the IR cut filter is removed and the characteristics of the lens and optical source characteristics are ignored.

# **Initial Settings, Custom Preset and Backup**

Initial Settings for the various functions of the FCB camera are indicated in the "Initial Settings" column. The "Custom Preset" column indicates whether the custom preset function can be used to store the settings. The function enables the stored settings to be recalled automatically when the camera is turned on. The "Back up at standby" column indicates whether the data is preserved even when the camera is in the standby mode.

Mode/Position setting	Initial Settings	Custom Preset	Back up at standby
Zoom Position	Wide end	0	0
D-Zoom On/Off	On	0	0
D-Zoom Separate/Combine	Combine	0	0
D-Zoom Position	00h	0	0
Focus Position	_	0	0
Focus Auto/Manual	Auto	0	0
Near Limit Setting	B000 (30 cm)	0	0
AF Sensitivity	Normal	0	0
AF Mode	Normal	0	0
AF Run Time	5 sec	0	0
AF Interval	5 sec	0	0
WB Mode	Auto	0	0
WB Data (Rgain, Bgain)	_	0	0
One Push WB Data		0	0
AE Mode	Full Auto	0	0
AE Response	01	0	0
Shutter Position	_	0	0
Maximum Shutter Limit	11h: 1/2000 (59.94, 29.97 fps)	0	0
	11h: 1/1750 (50, 25 fps)	-	
Minimum Shutter Limit	06h: 1/60 (59.94 fps)	0	0
	06h: 1/50 (50 fps)		
	05h: 1/30 (29.97 fps)		
	05h: 1/25 (25 fps)		
Slow Shutter Mode	Off	0	0
Slow Shutter Limit	04h: 1/15 (59.94, 29.97 fps)	0	0
Iris Position	04h: 1/12 (50, 25 fps)		
Gain Position		0	0
Bright Position		0	0
Exposure Compensation On/Off	Off	0	0
Exposure Compensation Amount	±0	0	0
BackLight On/Off	Off	0	0
Spot AE On/Off	Off	0	0
Spot AE Position Setting	X=8, Y=8	0	0
Aperture Level	07h	0	0
High Resolution Mode On/Off	Off	0	0
č		0	0
LR Reverse On/Off	Off	0	0
Freeze On/Off	Off	×	×

A circle "O" in this column signifies that the data is preserved. A cross " $\times$ " signifies that the data IS NOT preserved.

#### **Basic Functions**

Mode/Position setting	Initial Settings	Custom Preset	Back up at standby
Picture Effect	Off	0	0
ICR On/Off	Off	0	0
Auto ICR On/Off	Off	0	0
Auto ICR Threshold Level	0Eh	0	0
Camera Memory	Same as the initial value setting	×	0
Display On/Off	Off	0	0
Mute On/Off	Off	×	×
Auto ICR Alarm On/Off	Off	0	0
High Sensitivity Mode On/Off	Off	0	0
Gamma	0:standard	0	0
Defog On/Off	Off	0	0
NR Level	3	0	0
Image Stabilizer	Off	0	0
Gain Limit	Ch	0	0
Color Enhancement On/Off	Off	0	0
Color Enhancement Threshold Level	37h	0	0
Color Enhancement High Luminance Color Setting Y	48h	0	0
Color Enhancement Low Luminance Color Setting Y	3Ah	0	0
Low-Illumination Chroma Suppress	lh (Low)	0	0
Color Gain	4h (100%)	0	0
Color Hue	7h (0 degrees)	0	0
Title Display On/Off	Off	0	0
Title Setting	_	0	0
Mask Setting	_	0	0
Mask Display On/Off	Off	0	0
Mask Color Setting		0	0
Center Line Display On/Off	Off	0	0
E-Flip On/Off	Off	0	0
Privacy Zone On/Off	Off	0	0
Privacy Zone Setting	_	0	0
Camera ID	0000h	×	0
MD On/Off	Off	0	0
MD Display Setting	Off	0	0
MD Threshold Level	10h	0	0
MD Interval	1 sec	0	0
MD Window Setting	_	0	0
ZoomPos Continuous Output On/Off	Off	×	0
ZoomPos Continuous Output Interval	3Ch	×	0
HLC Level	Off	0	0
HLC Mask Level	Off	0	0

A circle "O" in this column signifies that the data is preserved.

A cross " $\times$  " signifies that the data IS NOT preserved.

#### Notes

- The number of times written to Non-volatile memory (when Custom Preset is executed) is limited.
- Privacy Zone Setting while digital zooming is not preserved by Custom Preset.

# Condition

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Address Set	0	0	0	0	0
IF_Clear	0	0	0	0	0
Command Cancel	0	0	0	0	0
Power On/Off	0	0	0	0	0

# Lens

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	Zoom Direct	Focus Direct	ZmFo Direct	Focus Auto
Zoom Tele/Wide/Stop	×	×	0	0	×	×	0	×	0
Zoom Direct	×	×	0	0	×	0	0	×	0
Zoom Focus Direct	×	×	0	0	×	×	×	0	×
D-Zoom On/Off	×	×	0	0	×	×	0	×	0
D-Zoom Separate/Combine	×	×	0	0	×	×	0	×	0
D-Zoom Tele/Wide/Stop	×	×	0	0	×	0	0	0	0
D-Zoom ×1/Max	×	×	0	0	×	0	0	0	0
D-Zoom Direct	×	×	0	0	×	0	0	0	0
Focus Far/Near/Stop	×	×	0	0	×	0	×	×	×
Focus Direct	×	×	0	0	×	0	0	×	×
Focus Auto/Manual	×	×	0	0	×	0	×	×	0
One Push AF	×	×	0	0	×	0	×	×	×
Focus Near Limit	×	×	0	0	×	0	×	×	0
AF Sensitivity Normal/Low	×	×	0	0	×	0	0	0	0
AF Mode Norm/Interval/Zoom	×	×	0	0	×	0	0	0	0
AF Activation Time/Interval Setting	×	×	0	0	×	0	0	0	0
Camera Memory Set/Reset	×	×	0	0	×	×	×	×	0
Camera Memory Recall	×	×	0	0	0	×	×	×	0
Lens Initialize	×	×	0	0	×	×	×	×	0

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Mode	Power Off	Power Off Initializing Power On Freeze On MemRe	Power On	Freeze On	MemRecall	WB Auto	Indoor	outdoor	Outdoor Auto	Sodium	Sodium Lamp Auto	Sodium Lamp	OnePush	ATW	Manual
WB Mode Switchover	×	×	0	0	×	0	0	0	0	0	0		0	0	0
One Push WB	×	×	0	0	×	×	×	×	×	×	×	×	0	×	×
RGain Setting	×	×	0	0	×	×	×	×	×	×	×	×	×	×	0
BGain Setting	×	×	0	0	×	×	×	×	×	×	×	×	×	×	0

# Exposure

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	AE Full Auto	AE Manual	Shutter Priority	Iris Priority	Bright
AE Full Auto	×	×	0	0	×	0	0	0	0	0
AE Manual	×	×	0	0	×	0	0	0	0	0
Shutter Priority	×	×	0	0	×	0	0	0	0	0
Iris Priority	×	×	0	0	×	0	0	0	0	0
Bright	×	×	0	0	×	0	×	0	×	0
Shutter Setting	×	×	0	0	×	×	0	0	×	×
Iris Setting	×	×	0	0	×	×	0	×	0	×
Gain Setting	×	×	0	0	×	×	0	×	×	×
Bright Setting	×	×	0	0	×	×	×	×	×	0
Slow Shutter On/Off	×	×	0	0	×	0	0	0	0	0
Exposure Compensation On/Off	×	×	0	0	×	0	0	0	0	0
Exposure Compensation Setting	×	×	0	0	×	0	0	0	0	0
BackLight On/Off	×	×	0	0	×	0	0	0	0	0
SpotAE On/Off	×	×	0	0	×	0	0	0	0	0
SpotAE Setting	×	×	0	0	×	0	0	0	0	0
Defog On/Off	×	×	0	0	×	0	0	0	0	0
Minimum Shutter On/Off	×	×	0	0	×	0	0	0	0	0
VE On/Off	×	×	0	0	×	0	0	0	0	0

#### **Basic Functions**

# Others

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Aperture Setting	×	×	0	×	×
High Resolution Mode On/Off	×	×	0	0	0
LR_Reverse On/Off	×	×	0	×	×
Freeze On/Off	×	×	0	0	×
Picture Effect Setting	×	×	0	×	×
ICR On/Off	×	×	0	×	×
Auto ICR On/Off	×	×	0	×	×
Auto ICR Threshold Level Setting	×	×	0	0	0
Auto ICR Alarm On/Off	×	×	0	×	0
Display On/Off	×	×	0	0	0
Mute On/Off	×	×	0	0	0
Title Setting	×	×	0	0	0
Mask On/Off	×	×	0	0	0
Mask Setting	×	×	0	0	0
MD On/Off	×	×	0	0	0
MD Function Setting	×	×	0	0	0
MD Window Setting	×	×	0	0	0
ID Write	×	×	0	0	0
Memory Save	×	×	0	0	0
Register Value Setting	×	×	0	0	0
Color Enhancement On/Off	×	×	0	×	×
NR Level Setting	×	×	0	0	0
Chroma Suppress	×	×	0	×	×
Color Gain	×	×	0	×	×
Color Hue	×	×	0	×	×

# **Command List**

# VISCA/RS-232C Commands

This Manual outlines an RS-232C control protocol and command list for certain Sony cameras from which control software can be developed. THIS CONTROL PROTOCOL AND COMMAND LIST IS PROVIDED BY SONY ON AN "AS-IS BASIS" WITHOUT WARRANTY OF ANY KIND. SONY DOES NOT WARRANT ANY PARTICULAR RESULT FROM THE USE OF THIS CONTROL PROTOCOL AND COMMAND LIST AND DISCLAIMS AND EXCLUDES ALL WARRANTIES. EXPRESS OR IMPLIED, WITH RESPECT TO THAT CONTROL PROTOCOL AND COMMAND LIST, INCLUDING, BUT NOT LIMITED TO, ANY OR ALL IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. IN FACT, SONY SPECIFICALLY ACKNOWLEDGES THAT SOFTWARE DEVELOPED BASED ON THIS CONTROL PROTOCOL AND COMMAND LIST MAY CAUSE MALFUNCTION OR DAMAGE TO HARDWARE AND SOFTWARE USED WITH IT (INCLUDING SONY HARDWARE AND SOFTWARE) AND SPECIFICALLY DISCLAIMS ANY LIABILITY FOR ANY SUCH MALFUNCTION OR DAMAGE. THIS CONTROL PROTOCOL AND COMMAND LIST SHOULD BE USED WITH CAUTION.

#### **Overview of VISCA**

In VISCA, the device outputting commands, for example, a computer, is called the controller. The device receiving the commands, an FCB camera is called the peripheral device. In VISCA, up to seven peripheral devices like the FCB camera can be connected to one controller using communication conforming to the RS-232C standard. The parameters of RS-232C are as follows.

- Communication speed: 9.6 kbps/19.2 kbps/ 38.4 kbps/57.6 kbps/115.2 kbps
- Data bits : 8
- Start bit : 1
- Stop bit : 1
- Non parity

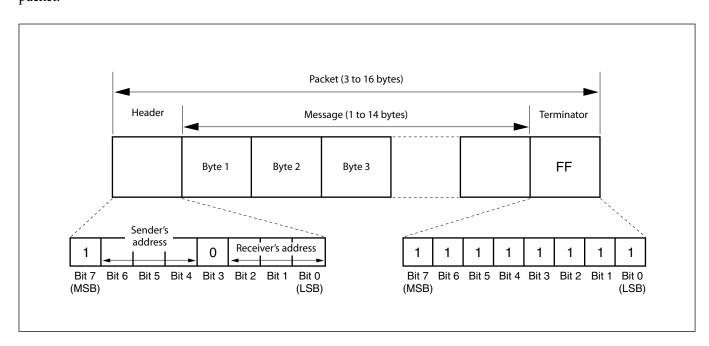
Flow control using XON/XOFF and RTS/CTS, etc., is not supported.

#### VISCA Communication Specifications

#### VISCA packet structure

The basic unit of VISCA communication is called a packet. The first byte of the packet is called the header and comprises the sender's and receiver's addresses. For example, the header of the packet sent to the FCB camera assigned address 1 from the controller (address 0) is hexadecimal 81h. The packet sent to the camera assigned address 2 is 82h. In the command list, as the header is 8X, input the address of the camera assigned address 1 is 90h. The packet from the camera assigned address 2 is A0h.

Some of the commands for setting cameras can be sent to all devices at one time (broadcast). In the case of broadcast, the header should be hexadecimal 88h. When the terminator is FFh, it signifies the end of the packet.



#### **Command and inquiry**

#### Command

Sends operational commands to the FCB camera.

Inquiry

Used for inquiring about the current state of the FCB camera.

	<b>Command Packet</b>	Note
Inquiry	8X QQ RR FF	$QQ^{1)} = Command/Inquiry,$
		RR <sup>2)</sup> = category code
• · · ·		

<sup>1)</sup> QQ = 01 (Command), 09 (Inquiry)

<sup>2)</sup> RR = 00 (Interface), 04 (camera 1), 06 (Pan/Tilt), 07 (camera 2)

X = 1 to 7: FCB camera address

#### **Responses for commands and inquiries**

#### • Acknowledge message

Returned by the FCB camera when it receives a command. No Acknowledge message is returned for inquiries.

#### • Completion message

Returned by the FCB camera when execution of commands or inquiries is completed. In the case of inquiry commands, it will contain reply data for the inquiry after the 3rd byte of the packet. If the Acknowledge message is omitted, the socket number will contain 0.

#### **Reply Packete**

AcknowledgeX0 4Y FFCompletion (Commands)X0 5Y FFCompletion (Inquiries)X0 5Y ... FFX = 9 to F: FCB camera address + 8, Y = socket number

#### • Error message

When a command could not be executed or failed, an error message is returned instead of the Acknowledge message. After an Acknowledge message, an error message may be returned if the process of some command (zoom, etc.) has not been completed.

When a inquiry command could not be executed or failed, an error message is returned instead of the completion message.

Error Packet	Description
X0 6Y 01 FF	Message length error (>14 bytes)
X0 6Y 02 FF	Syntax Error
X0 6Y 03 FF	Command buffer full
X0 6Y 04 FF	Command cancelled
X0 6Y 05 FF	No socket (to be cancelled)
X0 6Y 41 FF	Command not executable
X = 9 to F: FCB came	era address + 8, Y = socket number

#### Socket number

When command messages are sent to the FCB camera, send the next command message after waiting for the completion message or error message to return. However to deal with advanced uses, the FCB camera has two buffers (memories) for commands, so that up to two commands including the commands currently being executed can be received. When the FCB camera receives commands, it notifies the sender which command buffer was used using the socket number of the Acknowledge message. As the completion message or error message also has a socket number, it indicates which command has ended. Even when two command buffers are being used at any one time, an FCB camera management command and some inquiry messages can be executed. The Acknowledge message is not returned for these commands and inquiries, and only the completion message of socket number 0 is returned.

#### **Command execution cancel**

To cancel a command which has already been sent, send the Cancel command as the next command. To cancel one of any two commands which have been sent, use the cancel message.

#### **Cancel Packet**

Cancel 8X 2Y FF X = 1 to 7: FCB camera address, Y = socket number

An error message will be returned for this command, but this is not a fault. It indicates that the command has been canceled.

### **VISCA Device Setting Command**

Before starting control of the FCB camera, be sure to send the Address command and the IF\_Clear command using the broadcast function.

#### For VISCA network administration

#### Address

Sets an address of a peripheral device. Use when initializing the network, and receiving the following network change message.

#### • Network Change

Sent from the peripheral device to the controller when a device is removed from or added to the network. The address must be re-set when this message is received.

	Packet	Note
Address	88 30 01 FF	Always broadcasted.
Network Change	X0 38 FF	
X = 9 to F: FCB camera	address + 8	

#### **VISCA interface command**

#### • IF\_Clear

Clears the command buffers in the FCB camera and cancels the command currently being executed.

#### Command Packet Reply Packet

 IF\_Clear
 8X 01 00 01 FF
 X0 50 FF

 IF\_Clear (broadcast)
 88 01 00 01 FF
 88 01 00 01 FF

 X = 1 to 7: FCB camera address (For inquiry packet)
 X = 9 to F: FCB camera address +8 (For reply packet)

#### **VISCA interface and inquiry**

#### • CAM\_VersionInq

Returns information on the VISCA interface.

Inquiry	Inquiry Packet	Reply Packet	Description
CAM_VersionInq	8X 09 00 02 FF	YO 50 GG GG HH HH JJ JJ KK FF	GGGG = Vender ID
			(0020: Sony)
			HHHH = Model ID
			0700: FCB-ER8300/
			0701:FCB-CR8300
			JJJJ = ROM revision
			KK = Maximum socket #(02)

X = 1 to 7: FCB camera address (For inquiry packet)

X = 9 to F: FCB camera address +8 (For reply packet)

Command	Command Message	Reply Message	Comments
General Command	81 01 04 38 02 FF	90 41 FF (Acknowledge)	Returns Acknowledge when a command has been accepted, and
	(Example)	+90 51 FF (Completion)	Completion when a command has been executed.
		90 4 <u>2</u> FF 90 5 <u>2</u> FF	
	81 01 04 38 FF	90 60 02 FF (Syntax Error)	Accepted a command which is not supported or a command
	(Example)		lacking parameters.
	81 01 04 38 02 FF	90 60 03 FF	There are two commands currently being executed, and the
	(Example)	(Command Buffer Full)	command could not be accepted.
	81 01 04 08 02 FF	90 61 41 FF	Could not execute the command in the current mode.
	(Example)	(Command Not Executable)	
		90 6 <u>2</u> 41 FF	
Inquiry Command	81 09 04 38 FF	90 50 02 FF (Completion)	Acknowledge is not returned for the inquiry command.
	(Example)		
	81 09 05 38 FF	90 60 02 FF (Syntax Error)	Accepted an incompatible command.
	(Example)		
Address Set	88 30 <u>01</u> FF	88 30 <u>02</u> FF	Returned the device address to +1.
IF_Clear(Broadcast)	88 01 00 01 FF	88 01 00 01 FF	Returned the same command.
IF_Clear (For x)	8x 01 00 01 FF	z0 50 FF (Completion)	Acknowledge is not returned for this command.
Command Cancel	8x 2y FF	z0 6y 04 FF	Returned when the command of the socket specified is canceled.
		(Command Canceled)	Completion for the command canceled is not returned.
		z0 6y 05 FF (No Socket)	Returned when the command of the specified socket has already
			been completed or when the socket number specified is wrong.

### VISCA Camera-Issued Messages

#### Acknowledge/Completion Messages

	Command Messages	Comments
Acknowledge	z0 4y FF	Returned when the command is accepted.
	(y:Socket No.)	
Completion	z0 5y FF	Returned when the command has been executed.
	(y:Socket No.)	

z = Device address + 8

#### **Error Messages**

	Command Messages	Comments
Syntax Error	z0 60 02 FF	Returned when the command format is different or when a command with illegal
		command parameters is accepted.
Command Buffer Full	z0 60 03 FF	Indicates that two sockets are already being used (executing two commands) and the
		command could not be accepted when received.
Command Canceled	z0 6y 04 FF	Returned when a command which is being executed in a socket specified by the cancel
	(y:Socket No.)	command is canceled. The completion message for the command is not returned.
No Socket	z0 6y 05 FF	Returned when no command is executed in a socket specified by the cancel command,
	(y:Socket No.)	or when an invalid socket number is specified.
Command Not Executable	z0 6y 41 FF	Returned when a command cannot be executed due to current conditions. For example,
	(y:Socket No.)	when commands controlling the focus manually are received during auto focus.

#### Network Change Message

	Command Message	Comments
Network Change	z0 38 FF	Issued when power is being routed.

# **FCB Camera Commands**

### Command List (1/6)

Command Set	Command	Command Packet	Comments
AddressSet	Broadcast	88 30 01 FF	Address Setting
IF_Clear	-	8x 01 00 01 FF	I/F Clear
	Broadcast	88 01 00 01 FF	
CommandCancel	-	8x 2p FF	p: Socket No. (=1 or 2)
CAM_Power	On	8x 01 04 00 02 FF	Power On/Off
	Off (Standby)	8x 01 04 00 03 FF	
CAM_Zoom	Stop	8x 01 04 07 00 FF	
	Tele (Standard)	8x 01 04 07 02 FF	
	Wide (Standard)	8x 01 04 07 03 FF	
	Tele (Variable)	8x 01 04 07 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 07 3p FF	
	Direct	8x 01 04 47 0p 0q 0r 0s FF	pqrs: Zoom Position
			Min. 0000h
			Max. 4000h (In Separate mode)
			Max. 4000h (In Combine mode and DZoom=Off) Max. 59C0h (In Combine mode, DZoom=Super Resolution
			Zoom, and monitoring mode QFHD)
			Max. 6000h (In Combine mode, DZoom=Super Resolution
			Zoom, and monitoring mode FHD or less)
			Max. 7AC0h (In Combine mode and DZoom=On)
CAM_DZoom	On	8x 01 04 06 02 FF	Digital Zoom On/Off/Super Resolution Zoom
	Off	8x 01 04 06 03 FF	
	Super Resolution Zoom	8x 01 04 06 04 FF	
	Combine Mode	8x 01 04 36 00 FF	Optical/Digital Zoom Combined
	Separate Mode	8x 01 04 36 01 FF	Optical/Digital Zoom Separate
	Stop	8x 01 04 06 00 FF	
	Tele (Variable)	8x 01 04 06 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 06 3p FF	* Enabled during Separate Mode
	x1/Max	8x 01 04 06 10 FF	x1/MAX Magnification Switchover * Enabled during Separate Mode
	Direct	8x 01 04 46 00 00 0p 0q FF	pq: D-Zoom Position (00h to EBh)
			* Enabled during Separate Mode
CAM_Focus Mode	Auto Focus	8x 01 04 38 02 FF	AF On/Off
	Manual Focus	8x 01 04 38 03 FF	
	Auto/Manual	8x 01 04 38 10 FF	
CAM_Focus	Stop	8x 01 04 08 00 FF	
	Far (Standard)	8x 01 04 08 02 FF	
	Near (Standard)	8x 01 04 08 03 FF	
	Far (Variable)	8x 01 04 08 2p FF	p=0 (Low) to 7 (High)
	Near (Variable)	8x 01 04 08 3p FF	
	Direct	8x 01 04 48 0p 0q 0r 0s FF	pqrs: Focus Position
	One Push Trigger	8x 01 04 18 01 FF	One Push AF Trigger
	Near Limit	8x 01 04 28 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position
CAM_AFMode	Normal AF	8x 01 04 57 00 FF	AF Movement Mode
	Interval AF	8x 01 04 57 01 FF	
	Zoom Trigger AF	8x 01 04 57 02 FF	
	Active/Interval Time	8x 01 04 27 0p 0q 0r 0s FF	pq: Movement Time, rs: Interval

### Command List (2/6)

Command Set	Command	Command Packet	Comments
CAM_SpotFocus	On	8x 01 05 08 02 FF	pq: X (0h to Fh), rs: Y (0h to Fh)
	Off	8x 01 05 08 03 FF	
	Position	8x 01 05 68 0p 0q 0r 0s FF	
CAM_AFSensitivity	Normal	8x 01 04 58 02 FF	AF Sensitivity switching
	Low	8x 01 04 58 03 FF	
CAM_IRCorrection	Standard	8x 01 04 11 00 FF	Focus IR compensation data switching
	IR Light	8x 01 04 11 01 FF	
CAM_ZoomFocus	Direct	8x 01 04 47 0p 0q 0r 0s	pqrs: Zoom Position
CAM_Initialize	Lens	0t 0u 0v 0w FF 8x 01 04 19 01 FF	tuvw: Focus Position Lens Initialization Start
	Camera	8x 01 04 19 01 FF 8x 01 04 19 03 FF	Camera reset
CAM_WB	Auto	8x 01 04 19 05 FF 8x 01 04 35 00 FF	Normal Auto
CAM_WB		8x 01 04 35 01 FF	
	Indoor Outdoor		Indoor mode Outdoor mode
		8x 01 04 35 02 FF	
	One Push WB	8x 01 04 35 03 FF	One Push WB mode
	ATW	8x 01 04 35 04 FF	Auto Tracing White Balance
	Manual	8x 01 04 35 05 FF	Manual Control mode
	One Push Trigger	8x 01 04 10 05 FF	One Push WB Trigger
	Outdoor Auto	8x 01 04 35 06 FF	Outdoor auto
	Sodium Lamp Auto	8x 01 04 35 07 FF	Auto including sodium lamp source
	Sodium Lamp	8x 01 04 35 08 FF	Sodium lamp source fixed mode
	Sodium Lamp Outdoor Auto	8x 01 04 35 09 FF	Outdoor auto including sodium lamp source
CAM_WBTrigger	One Push Trigger	8x 01 04 10 05 FF	One Push WB Trigger
CAM_RGain	Reset	8x 01 04 03 00 FF	Manual Control of R Gain
	Up	8x 01 04 03 02 FF	
	Down	8x 01 04 03 03 FF	
	Direct	8x 01 04 43 00 00 0p 0q FF	pq: R Gain
CAM_BGain	Reset	8x 01 04 04 00 FF	Manual Control of B Gain
	Up	8x 01 04 04 02 FF	
	Down	8x 01 04 04 03 FF	
	Direct	8x 01 04 44 00 00 0p 0q FF	pq: B Gain
CAM_AE	Full Auto	8x 01 04 39 00 FF	Full Auto
	Manual	8x 01 04 39 03 FF	Manual Control mode
	Shutter Priority	8x 01 04 39 0A FF	Shutter Priority Auto Exposure mode
	Iris Priority	8x 01 04 39 0B FF	Iris Priority Auto Exposure mode
	Bright	8x 01 04 39 0D FF	Bright Mode (Manual control)
CAM_ LowLightBasisBrightness	On	8x 01 05 39 02 FF	p: Position
	Off	8x 01 05 39 03 FF	
	Position	8x 01 05 49 0p FF	
CAM_Shutter	Reset	8x 01 04 0A 00 FF	Shutter Setting
	Up	8x 01 04 0A 02 FF	
	Down	8x 01 04 0A 03 FF	
	Direct	8x 01 04 4A 00 00 0p 0q FF	pq: Shutter Position
CAM_MaxShutter	Limit	8x 01 05 2A 00 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutter	Limit	8x 01 05 2A 01 0p 0q FF	pq: Low-speed shutter limit
CAM_SlowShutter	On	8x 01 04 5A 02 FF	Slow Shutter On/Off
	Off	8x 01 04 5A 03 FF	
	Limit	8x 01 05 5A 0p 0q FF	pq: Slow Shutter Limit

# Command List (3/6)

Command Set	Command	Command Packet	Comments				
CAM_Iris	Reset	8x 01 04 0B 00 FF	Iris Setting				
	Up	8x 01 04 0B 02 FF	-				
	Down	8x 01 04 0B 03 FF					
	Direct	8x 01 04 4B 00 00 0p 0q FF	pq: Iris Position				
CAM_Gain	Reset	8x 01 04 0C 00 FF	Gain Setting				
	Up	8x 01 04 0C 02 FF	-				
	Down	8x 01 04 0C 03 FF	_				
	Direct	8x 01 04 4C 00 00 0p 0q FF	pq: Gain Position				
	Gain Limit	8x 01 04 2C 0p FF	p: Gain Limit				
	Gain Point	8x 01 05 4C 0p 0q FF	pq: Gain Point				
CAM_Bright	Reset	8x 01 04 0D 00 FF	Bright Setting				
	Up	8x 01 04 0D 02 FF	_				
	Down	8x 01 04 0D 03 FF	-				
	Direct	8x 01 04 4D 00 00 0p 0q FF	pq: Bright Position				
CAM_ExpComp	On	8x 01 04 3E 02 FF	Exposure Compensation On/Off				
	Off	8x 01 04 3E 03 FF	_				
	Reset	8x 01 04 0E 00 FF	Exposure Compensation Amount Setting				
	Up	8x 01 04 0E 02 FF	_				
	Down	8x 01 04 0E 03 FF	-				
	Direct	8x 01 04 4E 00 00 0p 0q FF	pq: ExpComp Position				
CAM_Backlight	On	8x 01 04 33 02 FF	Back Light Compensation On/Off				
- 0	Off	8x 01 04 33 03 FF					
CAM_SpotAE	On	8x 01 04 59 02 FF	Spot Auto Exposure Setting				
- 1	Off	8x 01 04 59 03 FF					
	Position	8x 01 04 29 0p 0q 0r 0s FF	pq: X (0h to Fh), rs: Y (0h to Fh)				
CAM_AE_Response	Direct	8x 01 04 5D pp FF	pp: Auto Exposure Response Setting (01h to 30h),				
1		11	default value: 01h				
CAM_VE	Off	8x 01 04 3D 03 FF	Off				
	VE On	8x 01 04 3D 06 FF	VE On				
	Set Parameter	8x 01 04 2D 00 0q 0r 0s 00 00 00 00 FF	<ul> <li>q: Display brightness level (0: Dark to 6: Bright)</li> <li>r: Brightness compensation selection (0: Very dark, 1: Dark, 2: Standard, 3: Bright)</li> <li>s: Compensation level (0: Low, 1: Mid, 2: High)</li> </ul>				
CAM_Defog	On	8x 01 04 37 02 0p FF	Defog On/Off				
	Off	8x 01 04 37 03 00 FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)				
CAM_Aperture	Reset	8x 01 04 02 00 FF	Aperture Control				
- 1	Up	8x 01 04 02 02 FF	_				
	Down	8x 01 04 02 03 FF	-				
	Level	8x 01 04 42 00 00 0p 0q FF	pq: Aperture Gain (00h to 0Fh)				
	Mode	8x 01 05 42 01 0p FF	p: Auto (0)/Manual (1) selection				
	BandWidth	8x 01 05 42 02 0p FF	<ul> <li>p: Bandwidth setting</li> <li>0: default (initial value)</li> <li>1: low bandwidth</li> <li>2: mid bandwidth</li> </ul>				
			3: wide bandwidth 4: broad bandwidth				
	Crispening	8x 01 05 42 03 0p FF	p: Crispening (0h to 7h)				
	H/V balance	8x 01 05 42 04 0p FF	p: H/V Balance (5h to 9h)				
	B/W balance	8x 01 05 42 05 0p FF	p: B/W Balance (0h to 4h)				
	Limit	8x 01 05 42 06 0p FF	p: Limit (0h to 7h)				
	HighLightDetail	8x 01 05 42 07 0p FF	p: High light detail (0h to 4h)				
	SuperLow	8x 01 05 42 08 0p FF	p: Super low emphasis (0h to 7h)				
CAM_HR	On	8x 01 04 52 02 FF	High Resolusion Mode On/Off				

# Command List (4/6)

Command Set	Command	Command Packet	Comments
CAM_NR	Noise Reduction	8x 01 04 53 0p FF	p: NR setting (00h: Off, 01h to 05h: level, 7Fh: 2D/3D manual setting)
2D NR/3D NR		8x 01 05 53 0p 0q FF	p: 2D NR level (0h to 5h), q: 3D NR level (0h to 5h)
CAM_Stabilizer	On	8x 01 04 34 02 FF	Image Stabilizer On/Off
	Off	8x 01 04 34 03 FF	
CAM_Gamma	—	8x 01 04 5B 0p FF	p: Gamma Setting (0: Standard, 1: Straight, 2: Pattern)
	Pattern	8x 01 05 5B 0p 0q 0r FF	pqr: Selection pattern (001h to 200h)
	Offset	8x 01 04 1E 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 40h)
CAM_HighSensitivity	On	8x 01 04 5E 02 FF	High Sensitivity mode On/Off
	Off	8x 01 04 5E 03 FF	
CAM_LR_Reverse	On	8x 01 04 61 02 FF	LR Reverse On/Off
	Off	8x 01 04 61 03 FF	
CAM_Freeze	On	8x 01 04 62 02 FF	Freeze On/Off
	Off	8x 01 04 62 03 FF	
CAM_PictureEffect	Off	8x 01 04 63 00 FF	Picture Effect Setting
	Black & White	8x 01 04 63 04 FF	_
CAM_PictureFlip	On	8x 01 04 66 02 FF	E-Flip On/Off
	Off	8x 01 04 66 03 FF	
CAM_ICR	On	8x 01 04 01 02 FF	ICR Mode On/Off
	Off	8x 01 04 01 03 FF	
CAM_AutoICR	On	8x 01 04 51 02 FF	Auto ICR Mode On/Off
	Off	8x 01 04 51 03 FF	
	Threshold	8x 01 04 21 00 00 0p 0q FF	pq: ICR On $\rightarrow$ Off Threshold Level (00h to FFh)
CAM	On	8x 01 04 31 02 FF	Auto ICR switching Alarm On/Off
_AutoICRAlarmReply	Off	8x 01 04 31 03 FF	
	(Reply)	y0 07 04 31 02 FF	ICR Off $\rightarrow$ On
		y0 07 04 31 03 FF	$ICR On \rightarrow Off$
CAM_Memory	Reset	8x 01 04 3F 00 0p FF	p: Memory Number (=0h to Fh)
	Set	8x 01 04 3F 01 0p FF	
	Recall	8x 01 04 3F 02 0p FF	
CAM_Custom	Reset	8x 01 04 3F 00 7F FF	Starts up in this mode when the power is turned on.
	Set	8x 01 04 3F 01 7F FF	
	Recall	8x 01 04 3F 02 7F FF	
CAM_MemSave	Write	8x 01 04 23 0X 0p 0q 0r 0s FF	X: 00h to 07h (Address), total 16 byte pqrs: 0000h to FFFFh (Data)
CAM_Display	On	8x 01 04 15 02 FF	Display On/Off
	Off	8x 01 04 15 03 FF	
	On/Off	8x 01 04 15 10 FF	
CAM_MultiLineTitle	Title Set1	8x 01 04 73 1L 00 nn pp qq 00 00 00 00 00 00 FF	L: Line Number, nn: H-position pp: Color, qq: Blink
	Title Set2	8x 01 04 73 2L mm nn pp qq rr ss tt uu vv ww FF	L: Line Number, mnpqrstuvw: Setting of characters (1 to 10)
	Title Set3	8x 01 04 73 3L mm nn pp qq rr ss tt uu vv ww FF	L: Line Number, mnpqrstuvw: Setting of characters (11 to 20)
	Title Clear	8x 01 04 74 1p FF	Title Setting clear (p: 0h to Ah, F= all lines)
	On	8x 01 04 74 2p FF	Title display On/Off (p: 0h to Ah, F= all lines)
	Off	8x 01 04 74 3p FF	

# Command List (5/6)

Command Set	Command	Command Packet	Comments			
CAM_Mute	On	8x 01 04 75 02 FF	Muting On/Off			
	Off	8x 01 04 75 03 FF	-			
	On/Off	8x 01 04 75 10 FF	-			
CAM_PrivacyZone	SetMask	8x 01 04 76 mm nn	mm: Mask Settings			
		Or Or Os Os FF	nn 00: Modify, 01: New			
			rr: W, ss: H			
	SetMaskTable	8x 01 05 70 0p FF	p: Table (0h to 1h)			
	Display	8x 01 04 77 pp pp pp pF FF	Mask Display On/Off			
			pp pp pp pp: Mask Settings (0: Off, 1: On)			
	SetMaskColor	8x 01 04 78 pp pp pp pp	pp pp pp pp: Mask Color Settings			
		qq rr FF	qq: Color Setting when 0 is selected rr: Color Setting when 1 is selected			
	SetPanTiltAngle	8x 01 04 79 0p 0p 0p	Pan/Tilt Angle Settings			
		0q 0q 0q FF	ppp: Pan			
			qqq: Tilt			
	SetPTZMask	8x 01 04 7B mm 0p 0p 0p	Pan/Tilt/Zoom Settings for Mask			
		0q 0q 0q 0r 0r 0r 0r FF	ppp: Pan, qqq: Tilt, rrrr: Zoom, mm: Mask Settings			
	Non_InterlockMask	8x 01 04 6F mm	mm: Non_Interlock Mask Settings			
	CenterLineOff	0p 0p 0q 0q 0r 0r 0s 0s FF 8x 01 04 7C 03 FF	pp: X, qq: Y, rr: W, ss: H			
			Center Line Display Off			
	CenterLineOn	8x 01 04 7C 04 FF	Center Line Display On			
CAM_IDWrite	_	8x 01 04 22 0p 0q 0r 0s FF	pqrs: Camera ID (=0000h to FFFFh)			
CAM_MD	On	8x 01 04 1B 02 FF	MD On/Off			
	Off	8x 01 04 1B 03 FF				
	Function Set	8x 01 04 1C 0m 0n 0p 0q 0r 0s FF	m: Display mode			
			n: Detection Frame Set (00h to 0Fh)			
			pq: Threshold Level (00h to FFh)			
			rs: Interval Time set (00h to FFh)			
	Window Set	8x 01 04 1D 0m 0p 0q 0r 0s FF	m: Select Detection Frame (0, 1, 2, 3)			
			p: Start Horizontal Position (00h to 0Fh)			
			q: Start Vertical Position (00h to 07h)			
			r: Stop Horizontal Position (01h to 10h) s: Stop Vertical Position (01h to 08h)			
	Alarm (Reply)	y0 07 04 1B 0p FF	p: Detection Frame Number			
CAM_Continuous	On	8x 01 04 69 02 FF	Zoom Position data Continuous Output On/Off			
ZoomPosReply						
	Off	8x 01 04 69 03 FF				
	(Reply)	y0 07 04 69 0p 0p 0q 0q 0q 0q FF	pp: D-Zoom Position			
			* 00: When Zoom Mode is Combine qqqq: Zoom Position			
CAM_ZoomPos		8x 01 04 6A 00 00 0p 0p FF	pp: Interval Time [V cycle]			
ReplyIntervalTimeSet	_		pp. interval fille [v cycle]			
CAM_Continuous	On	8x 01 04 16 02 FF	Focus Position data Continuous Output On/Off			
FocusPosReply	Off	8x 01 04 16 03 FF	-			
	(Reply)	y0 07 04 16 00 00 0p 0p 0p 0p FF	pppp: Focus Position			
CAM_FocusPosReply		8x 01 04 1A 00 00 0p 0p FF	pp: Interval Time [V cycle]			
IntervalTimeSet			pp. interval finde (v eyeld)			
CAM_RegisterValue	_	8x 01 04 24 mm 0p 0p FF	mm: Register No. (=00h to 7Fh)			
-			pp: Register Value (=00h to FFh)			
CAM_ColorEnhance	Parameter Set	8x 01 04 20 mm 00 pp 40 40 ss 40 40 FF	mm: Threshold level			
			pp: Y fixed color for high-intensity			
			ss: Y fixed color for low-intensity			
			Each parameter setting 00h to 7Fh			
	On	8x 01 04 50 02 FF	Color Enhancement On/Off			
	Off	8x 01 04 50 03 FF				

# Command List (6/6)

Command Set	Command	Command Packet	Comments				
CAM_ChromaSuppress	-	8x 01 04 5F pp FF	pp: Chroma Suppress setting level				
			00: Off				
			01h to 03h: On (3 levels).				
			Effect increases as the level number increases.				
CAM_ColorGain	Direct	8x 01 04 49 00 00 00 0p FF	p: Color Gain Setting 0h (60%) to Eh (200%)				
CAM_ColorHue	Direct	8x 01 04 4F 00 00 00 0p FF	p: Color Hue Setting 0h (-14 degrees) to Eh (+14 degrees)				
CAM_ExExpComp	Reset	8x 01 04 1F 0E 00 00 FF	Exposure compensation reset				
(Extended command)	Up	8x 01 04 1F 0E 02 pp FF	Exposure compensation up				
			pp: Step number				
			pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Down	8x 01 04 1F 0E 03 pp FF	Exposure compensation down				
			pp: Step number				
			pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Direct	8x 01 04 1F 4E 00 00 0p 0q FF	Set the exposure compensation to the specified level				
			pq: Level pq=00h to FFh				
CAM_ExAperture	Reset	8x 01 04 1F 02 00 00 FF	Aperture control reset				
(Extended command)			1				
(Extended commund)	Up	8x 01 04 1F 02 02 pp FF	Aperture control up pp: Step number				
			pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Down	8x 01 04 1F 02 03 pp FF	Aperture control down				
	Down	0x 01 04 11 02 05 pp 11	pp: Step number				
			pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Direct	8x 01 04 1F 42 00 00 0p 0q FF	Set the aperture control to the specified level				
			pq: Level				
			pq=00h to FFh				
CAM_ExAutoICR	Threshold	8x 01 04 1F 21 00 00 0p 0q FF	pq: ICR ON $\rightarrow$ OFF threshold level when Auto ICR				
(Extended command)	(ON→OFF)		pq=00h to FFh				
	On Level	8x 01 04 1F 21 01 00 0r 0s FF	pq: ICR OFF→ON threshold level when Auto ICR pq=00h to 16h				
CAM_ExColorGain	Direct	8x 01 04 1F 49 00 00 0p 0q FF	Color Gain Setting				
(Extended command)	Direct	8x 01 04 11 49 00 00 0p 0q 11	pq: Gain setting level				
(Extended command)			pq=00h (0%) to FFh (200%)				
CAM_ExColorHue	Direct	8x 01 04 1F 4F 00 00 0p 0q FF	Color Hue Setting				
(Extended command)			pq: Phase setting level				
			pq=00h (-14 degrees) to FFh (14 degrees)				
CAM_HLC	Parameter Set	8x 01 04 14 0p 0q FF	p: HLC level (0: Off, 1: On) q: HLC mask level (0: Off, 1: On)				
CAM_ColorBar	Off	8x 01 7E 04 7D 00 FF	-				
	On (Color bar 100%	8x 01 7E 04 7D 01 FF	1				
	8 colors)						
	On (Color bar 100%	8x 01 7E 04 7D 02 FF					
	7 colors)						
	On (Gray scale)	8x 01 7E 04 7D 03 FF	]				
CAM_ePT	On	8x 01 7E 06 00 02 FF					
	Off	8x 01 7E 06 00 03 FF					
	Absolute Position	8x 01 7E 06 20 00 00 0y 0y 0y 0y 0z 0z 0z	yyyy: Pan Position, zzzz: Tilt Position				
		0z FF	*Supplementary explanation:				
			Pan Position is specified in units of 6 pixels and Tilt Position				
			is specified in units of 4.5 pixels (cut off after the decimal				
			point)				
	1	1					

# Inquiry Command List (1/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_PowerInq	8x 09 04 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off (Standby)
CAM_ZoomPosInq	8x 09 04 47 FF	y0 50 0p 0q 0r 0s FF	pqrs: Zoom Position
CAM_DZoomModeInq	8x 09 04 06 FF	y0 50 02 FF	D-Zoom On
		y0 50 03 FF	D-Zoom Off
CAM_DZoomC/SModeInq	8x 09 04 36 FF	y0 50 00 FF	Combine Mode
		y0 50 01 FF	Separate Mode
CAM_DZoomPosInq	8x 09 04 46 FF	y0 50 00 00 0p 0q FF	pq: D-Zoom Position
CAM_FocusModeInq	8x 09 04 38 FF	y0 50 02 FF	Auto Focus
		y0 50 03 FF	Manual Focus
CAM_FocusPosInq	8x 09 04 48 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Position
CAM_FocusNearLimitInq	8x 09 04 28 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position
CAM_SpotFocusModeInq	8x 09 05 08 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotFocusPosInq	8x 09 05 68 FF	y0 50 0p 0q 0r 0s FF	pq: X, rs: Y
CAM_AFSensitivityInq	8x 09 04 58 FF	y0 50 02 FF	AF Sensitivity Normal
		y0 50 03 FF	AF Sensitivity Low
CAM_AFModeInq	8x 09 04 57 FF	y0 50 00 FF	Normal AF
		y0 50 01 FF	Interval AF
		y0 50 02 FF	Zoom Trigger AF
CAM_AFTimeSettingInq	8x 09 04 27 FF	y0 50 0p 0q 0r 0s FF	pq: Movement Time, rs: Interval
CAM_	8x 09 05 39 FF	y0 50 02 FF	On
LowLightBasisBrightnessInq		y0 50 03 FF	Off
CAM_LowLightBasis	8x 09 05 49 FF	y0 50 0p FF	p: Position
BrightnessPosInq			
CAM_IRCorrectionInq	8x 09 04 11 FF	y0 50 00 FF	Standard
		y0 50 01 FF	IR Light
CAM_WBModeInq	8x 09 04 35 FF	y0 50 00 FF	Auto
		y0 50 01 FF	Indoor
		y0 50 02 FF	Outdoor
		y0 50 03 FF	One Push WB
		y0 50 04 FF	ATW
		y0 50 05 FF	Manual
		y0 50 06 FF	Outdoor Auto
		y0 50 07 FF	Sodium Lamp Auto
		y0 50 08 FF	Sodium Lamp
CAM Desiglar	8	y0 50 09 FF	Sodium Lamp Outdoor Auto
CAM_RGainInq	8x 09 04 43 FF	y0 50 00 00 0p 0q FF y0 50 00 00 0p 0q FF	pq: R Gain
CAM_BGainInq	8x 09 04 44 FF	, 11	pq: B Gain Full Auto
CAM_AEModeInq	8x 09 04 39 FF	y0 50 00 FF y0 50 03 FF	Manual
		y0 50 0A FF	Shutter Priority
		y0 50 0B FF	Iris Priority
		y0 50 0D FF	Bright
CAM_ShutterPosInq	8x 09 04 4A FF	y0 50 00 00 0p 0q FF	pq: Shutter Position
CAM_ShutterInq	8x 09 05 2A 00 FF	y0 50 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutterInq	8x 09 05 2A 00 FF 8x 09 05 2A 01 FF		pq: Low-speed shutter limit
CAM_MinShutterInq	8x 09 05 2A 01 FF 8x 09 04 5A FF	y0 50 0p 0q FF y0 50 02 FF	On
Signal Slowshutter Ind	0A U7 U4 JA I'I'	y0 50 02 FF y0 50 03 FF	Off
CAM_SlowShutterLimitInq	8x 09 05 5A FF	y0 50 03 FF y0 50 0p 0q FF	pq: Slow Shutter Limit
CANI_SIOWSHULTERLIMITING	0X U7 U3 3A FF	yo 30 op 04 FF	pq: slow shutter Linit

# Inquiry Command List (2/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_IrisPosInq	8x 09 04 4B FF	y0 50 00 00 0p 0q FF	pq: Iris Position
CAM_GainPosInq	8x 09 04 4C FF	y0 50 00 00 0p 0q FF	pq: Gain Position
CAM_GainLimitInq	8x 09 04 2C FF	y0 50 0q FF	p: Gain Limit
CAM_GainPointInq	8x 09 05 4C FF	y0 50 0p 0q FF	pq: Gain Point
CAM_BrightPosInq	8x 09 04 4D FF	y0 50 00 00 0p 0q FF	pq: Bright Position
CAM_ExpCompModeInq	8x 09 04 3E FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ExpCompPosInq	8x 09 04 4E FF	y0 50 00 00 0p 0q FF	pq: ExpComp Position
CAM_BackLightModeInq	8x 09 04 33 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotAEModeInq	8x 09 04 59 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotAEPosInq	8x 09 04 29 FF	y0 50 0p 0q 0r 0s FF	pq: X Position, rs: Y Position
CAM_VEModeInq	8x 09 04 3D FF	y0 50 03 FF	Off
		y0 50 06 FF	VE On
CAM_VEParameterInq	8x 09 04 2D FF	y0 50 00 0q 0r 0s 0t 0u 00 00 FF	q: Display brightness level (0: Dark to 6: Bright)r: Brightness compensation selection (0: Very dark,1: Dark, 2: Standard, 3: Bright)s: Compensation level (00h: Low, 01h: Mid, 02h: High)tu: Always 0
CAM_AEResponseInq	8x 09 04 5D FF	y0 50 pp FF	pp: 01h to 30h
CAM_DefogInq	8x 09 04 37 FF	y0 50 02 0p FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)
		y0 50 03 00 FF	Defog Off
CAM_ApertureInq	8x 09 04 42 FF	y0 50 00 00 0p 0q FF	pq: Aperture Gain
CAM_ApertureModeInq	8x 09 05 42 01 FF	x0 50 0p FF	p: Auto (0), Manual (1)
CAM_ApertureBandwidthInq	8x 09 05 42 02 FF	x0 50 0p FF	p: Bandwidth
CAM_ApertureCrispeningInq	8x 09 05 42 03 FF	x0 50 0p FF	p: Crispening
CAM_ApertureH/VBalance	8x 09 05 42 04 FF	x0 50 0p FF	p: H/V Balance
CAM_ApertureB/WBalance	8x 09 05 42 05 FF	x0 50 0p FF	p: B/W Balance
CAM_ApertureLimitInq	8x 09 05 42 06 FF	x0 50 0p FF	p: Limit
CAM_ ApertureHighLightDetailInq	8x 09 05 42 07 FF	x0 50 0p FF	p: High light detail
CAM_ApertureSuperLowInq	8x 09 05 42 08 FF	x0 50 0p FF	p: Super low emphasis
CAM_HRModeInq	8x 09 04 52 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_NRInq	8x 09 04 53 FF	y0 50 0p FF	Noise Reduction p: 00h to 05h, 7Fh
CAM_NR2D3DInq	8x 09 05 53 FF	y0 50 0p 0q FF	p: 2D NR Level, q: 3D NR Level
CAM_StabilizerModeInq	8x 09 04 34 FF	y0 05 02 FF	On
		y0 05 03 FF	Off
CAM_GammaInq	8x 09 04 5B FF	y0 50 0p FF	Gamma p: 00h, 01h
CAM_GammaPatternInq	8x 09 05 5B FF	y0 50 0p 0q 0r FF	pqr: Selection pattern
CAM_GammaOffsetInq	8x 09 04 1E FF	y0 50 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 10h)
CAM_HighSensitivityInq	8x 09 04 5E FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_LR_ReverseModeInq	8x 09 04 61 FF	y0 50 02 FF	On
		y0 50 03 FF	Off

# Inquiry Command List (3/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_FreezeModeInq	8x 09 04 62 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_PictureEffectModeInq	8x 09 04 63 FF	y0 50 00 FF	Off
		y0 50 04 FF	Black & White
CAM_PictureFlipModeInq	8x 09 04 66 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ICRModeInq	8x 09 04 01 FF	y0 50 02 FF	On
-		y0 50 03 FF	Off
CAM_AutoICRModeInq	8x 09 04 51 FF	y0 50 02 FF	On
_ 1		y0 50 03 FF	Off
CAM_AutoICRThresholdInq	8x 09 04 21 FF	y0 50 00 00 0p 0q FF	pq: ICR On $\rightarrow$ Off Threshold Level
CAM_AutoICRAlarmReplyInq	8x 09 04 31 FF	y0 50 02 FF	On
ormi_rutororumarinitapi/inq		y0 50 03 FF	Off
CAM_MemoryInq	8x 09 04 3F FF	y0 50 pp FF	pp: Memory number recalled last
CAM MemSaveIng	8x 09 04 23 0X FF	y0 50 0p 0q 0r 0s FF	X: 00h to 07h (Address)
GAWI_Membaveniq	0x 0) 04 23 0X 11		pqrs: 0000h to FFFFh (Data)
CAM_DisplayModeInq	8x 09 04 15 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_MuteModeInq	8x 09 04 75 FF	y0 50 02 FF	On
1		y0 50 03 FF	Off
CAM_SetMaskTableInq	8x 09 05 70 FF	y0 50 0m FF	m: Table
CAM_PrivacyDisplayInq	8x 09 04 77 FF	y0 50 pp pp pp FF	pp pp pp pp: Mask Display (0: Off, 1: On)
CAM_PrivacyPanTiltInq	8x 09 04 79 FF	y0 50 0p 0p 0p 0q 0q 0q FF	ppp: Pan
CAM_rivacyrainining	0X 09 04 79 11		qqq: Tilt
CAM_PrivacyPTZInq	8x 09 04 7B mm FF	y0 50 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r	mm: Mask Settings
		FF	ppp: Pan
			qqq: Tilt
			rrrr: Zoom
CAM_PrivacyMonitorInq	8x 09 04 6F FF	y0 50 pp pp pp pp FF	pp pp pp pp: Mask is displayed now.
CAM_IDInq	8x 09 04 22 FF	y0 50 0p 0q 0r 0s FF	pqrs: Camera ID
CAM_VersionInq	8x 09 00 02 FF	y0 50 00 20	mnpq: Model Code (04xx)
		mn pq rs tu vw FF	rstu: ROM version
		0.50.02.00	vw: Socket Number (=02)
CAM_MDModeInq	8x 09 04 1B FF	y0 50 02 FF	On .
	-	y0 50 03 FF	Off
CAM_MDFunctionInq	8x 09 04 1C FF	y0 50 0m 0n 0p 0q 0r 0s FF	m: Display mode
			n: Detection Frame Set (00h to 0Fh) pq: Threshold Level (00h to FFh)
			rs: Interval Time set (00h to FFh)
CAM_MDWindowInq	8x 09 04 1D 0m FF	y0 50 0p 0q 0r 0s FF	m: Select Detection Frame (0, 1, 2, 3)
- 1		, , , , , , , , , , , , , , , , , , , ,	p: Start Horizontal Position (00h to 0Fh)
			q: Start Vertical Position (00h to 07h)
			r: Stop Horizontal Position (01h to 10h)
			s: Stop Vertical Position (01h to 08h)
CAM_ContinuousZoomPos	8x 09 04 69 FF	y0 50 02 FF	On
ReplyModeInq		y0 50 03 FF	Off
CAM_ZoomPosReply	8x 09 04 6A FF	y0 50 00 00 0p 0p FF	pp: Interval Time
IntervalTimeInq	0 00 04 14 PP	-0.50.02 EE	
CAM_Continuous	8x 09 04 16 FF	y0 50 02 FF	On .
FocusPosReplyModeInq		y0 50 03 FF	Off
CAM_FocusReply	8x 09 04 1A FF	y0 50 00 00 0p 0p FF	pp: Interval Time
IntervalTimeInq CAM_RegisterValueInq	8x 09 04 24 mm FF	y0 50 0p 0p FF	mm: Register No. (=00h to 7Fh)
Same and a second surgering		1,000 ch oh 11	pp: Register Value (=00h to FFh)
	1		11

# Inquiry Command List (4/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments			
CAM_ColorEnhanceInq	8x 09 04 20 FF	y0 50 mm 00 pp 40 40 ss 40 40 FF	mm: Threshold level			
			pp: Y fixed color for high-intensity			
			ss: Y fixed color for low-intensity			
	8x 09 04 50 FF	y0 50 02 FF	On			
		y0 50 03 FF	Off			
CAM_ChromaSuppressInq	8x 09 04 5F FF	y0 50 pp FF	pp: Chroma Suppress setting level			
CAM_ColorGainInq	8x 09 04 49 FF	y0 50 00 00 00 0p FF	p: Color Gain Setting 0h (60%) to Eh (200%)			
CAM_ColorHueInq	8x 09 04 4F FF	y0 50 00 00 00 0p FF	p: Color Hue Setting 0h (- 14 degrees) to Eh (+ 14 degrees)			
CAM_TempInq	8x 09 04 68 FF	Y0 50 00 00 0p 0q FF	pq: Lens Temperature			
CAM_ExExpCompPosInq	8x 09 04 1F 4E FF	y0 50 00 00 0p 0q FF	pq: Exposure compensation level pq = 00h to FFh			
(Extended command)						
CAM_ExApertureInq	8x 09 04 1F 42 FF	y0 50 00 00 0p 0q FF	pq: Aperture control level			
(Extended command)			pq=00h to FFh			
CAM_ExColorGainInq	8x 09 04 1F 49 00 FF	y0 50 0p 0q FF	pq: Gain setting level, pq: 00h (0%) to FFh (200%)			
(Extended command)						
CAM_ExColorHueInq	8x 09 04 1F 4F 00 FF	y0 50 0p 0q FF	pq: Phase setting level			
(Extended command)			pq: 00h (-14 degree) to FFh (+14 degree)			
CAM_ExAutoICRThresholdInq	8x 09 04 1F 21 00 FF	y0 50 00 00 0p 0q FF	pq: ICR ON→OFF threshold level when Auto ICR			
(Extended command)			pq = 00h to FFh			
CAM_ExAutoICROnLevelInq	8x 09 04 1F 21 01 FF	y0 50 00 00 0p 0q FF	pq: ICR OFF→ON threshold level when Auto ICR			
(Extended command)			pq = 00h to 1Ch			
CAM_HLCInq	8x 09 04 14 FF	y0 50 0p 0q FF	p: HLC level (0: Off, 1: On)			
			q: HLC mask level (0: On, 1: Off)			
CAM_ColorBarInq	8x 09 7E 04 7D FF	y0 50 00 FF	Off			
		y0 50 01 FF	Color bar 100% 8 colors			
		y0 50 02 FF	Color bar 75% 7 colors			
		y0 50 03 FF	Gray scale			
CAM_ePTModeInq	8x 09 7E 06 00 FF	y0 50 02 FF	On			
		y0 50 03 FF	Off			
CAM_ePTPositionInq	8x 09 7E 06 20 FF	y0 50 00 00 0y 0y 0y 0y 0z 0z 0z 0z FF	yyyy: Pan Position, zzzz: Tilt Position			

# **Block Inquiry Command List**

# Lens Control System Inquiry Commands .....Command Packet 8x 09 7E 7E 00 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments	
	7			7	0		7	0	
	6		6		6	0		6	0
	5	Destination Address		5	0		5	0	
0	4			4	0		4	0	
0	3		6	3		12	3	0	
	2	Source Address		2	Focus Near Limit (H)		2	0	
	1	Source Address		1	Focus Near Limit (H)		1	0	
	0			0			0	0	
	7	0 Completion Message (50h)		7	0		7	0	
	6	1		6	0		6	0	
	5	0		5	0		5	DZoomMode 0: Combine	
1	4	1	7	4	0			1: Separate	
1	3	0		3			4	0: Normal 1: Interval	
	2	0		2		13	3	2: Zoom Trigger	
	1	0		1	Focus Near Limit (L)		2	AF Sensitivity 0: Low	
	0	0		0				1: Normal	
	7	0		7	0		1	Digital Zoom 1: On 0: Off	
	6	0		6	0		0	Focus Mode 0: Manual 1: Auto	
	5	0		5	0		7	0	
2	4	0		4	0		6	0	
2	3		8	3			5	0	
	2	Zoom Position (HH)		2	Focus Position (HH)		4	0	
	1			1	Focus Position (HH)		3	Low Contrast Detection 1: Yes	
	0			0		14		0: No	
	7	0	0 7 0 14	2	Camera Memory Recall				
	6	0		6	0			1: Executing 0: Stopped	
	5	0		5	0		1	Focus Command 1: Executing	
3	4	0	9	4	0			0: Stopped	
5	3			3			0	Zoom Command 1: Executing	
	2	Zoom Position (HL)		2	Focus Position (HL)			0: Stopped	
	1			1	Tocus Tosition (TIL)		7	1 Terminator (FFh)	
	0			0			6	1	
	7	0		7	0		5	1	
	6	0		6	0	15	4	1	
	5	0		5	0		3	1	
4	4	0	10	4	0		2	1	
T	3		10	3			1	1	
	2	Zoom Position (LH)		2	Focus Position (LH)		0	1	
	1			1					
	0			0					
	7	0		7	0				
	6	0		6	0				
	5	0		5	0				
5	4	0	11	4	0				
5	3			3					
	2	Zoom Position (LL)		2	Focus Position (LL)				
	1	L Zoom Position (LL)	rocus rosmon (LL)						
	0			0					

# Camera Control System Inquiry Commands .....Command Packet 8x 09 7E 7E 01 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	Destination Address		6	0		6	0
	5	Destination Address		5	0		5	0
0	4		6	4	0	12	4	0
0	3		6	3		12	3	
	2	Source Address		2	M/D M - J-		2	Cuin Desition
	1	Source Address		1	WB Mode		1	Gain Position
	0			0			0	
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
1	4	1	7	4	0	13	4	
1	3	0	<b>_</b>	3		15	3	
	2	0		2	Aperture Gain		2	Bright Position
	1	0		1	Aperture Gam		1	
	0	0		0			0	
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
2	4	0	8	4		14	4	0
2	3		0	3			3	
	2	R Gain (H)		2	Exposure Mode		2	Exposure Comp. Position
	1			1			1	Exposure Comp. rosition
	0			0			0	
	7	0		7	0		7	1 Terminator (FFh)
	6	0		6	0		6	1
	5	0		5	High Resolution 1: On 0: Off		5	1
3	4	0	9	4	VE 1: On 0: Off	15	4	1
5	3			3	Spot AE 1: On 0: Off	15	3	1
	2	R Gain (L)		2	Backlight 1: On 0: Off		2	1
	1			1	Exposure Comp. 1: On 0: Off		1	1
	0			0	Slow Shutter 1: On 0: Off		0	1
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
4	4	0	10	4				
	3			3				
	2	B Gain (H)		2	Shutter Position			
	1			1				
	0			0				
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
5	4	0	11	4				
	3			3				
	2	B Gain (L)		2	Iris Position			
	1			1				
	0			0				

# 

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6			6	0		6	0
	5	Destination Address		5	0		5	0
0	4			4	0		4	Memory 1: Provided 0: Not
0	3		6	3	0			provided
	2	Course Address		2	0	10	3	0
	1	Source Address		1	0	12	2	ICR 1: Provided 0: Not
	0			0	0			provided
	7	0 Completion Message (50h)		7	0		1	Stabilizer 1: Provided 0: Not provided
	6	1		6	0		0	System 1: 1/50, 1/25 0: 1/59.94,
	5	0		5	0			1/29.97
1	4	1	7	4	0		7	0
	3	0		3	0		6	0
	2	0		2	0		5	0
	1	0		1	0	10	4	0
	0	0		0	0	13	3	0
	7	0		7	0		2	0
	6	0		6	0		1	0
	5	0		5	0		0	0
2	4	0		4	0		7	0
2	3	Auto ICR Alarm (1: On, 0: Off)	8	3			6	0
	2	Auto ICR 1: On 0: Off		2			5	0
	1	0		1	Camera ID (HH)		4	0
	0	Power 1: On 0: Off		0		14	3	0
	7	0	0 7 0	2	0			
	6	Stabilizer 1: On 0: Off		6	0		1	0
	5	0		5	0		0	0
2	4	ICR 1: On 0: Off		4	0		7	1 Terminator (FFh)
3	3	Freeze 1: On 0: Off	9	3			6	1
	2	LR Reverse 1: On 0: Off		2			5	1
	1	0		1	Camera ID (HL)	15	4	1
	0	0		0		15	3	1
	7	0		7	0		2	1
	6	0		6	0		1	1
	5	Privacy Zone 1: On 0: Off		5	0		0	1
4	4	Mute 1: On 0: Off	10	4	0			
4	3	Title Display 1: On 0: Off	10	3				
	2	Display 1: On 0: Off		2	Camera ID (LH)			
	1	0		1				
	0	0		0				
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
5	4	0	11	4	0			
5	3			3				
	2	Picture Effect Mode		2	Camera ID (LL)			
	1	FICTURE Effect MODE		1	Camera ID (LL)			
	0			0				47

# Extended Function1 Query Command .....Command Packet 8x 09 7E 7E 03 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	Destination Address		6	0		6	
	5	Destination Address		5	0		5	Color Gain (0h (60%) to
0	4			4	0		4	Eh (200%))
0	3		6	3			3	
	2	a + 11		2		11	2	Advanced Privacy
	1	Source Address		1	AF Interval Time (H)			(1: Provided, 0: Not provided)
	0			0			1	Reserved
	7	0 Completion Message (50h)		7	0		0	E-Flip (1: Provided, 0: Not provided)
	6	1		6	0		7	0
	5	0		5	0		6	0
1	4	1	7	4	0		5	0
	3	0		3			4	
	2	0		2		12	3	
	1	0		1	AF Interval Time (L)		2	AE Response
	0	0		0			1	The recipion of
	7	0		7	0		0	
	6	0		6	0		7	0
	5	0		5	0		6	0
					+			Comme
2	4	0	8	4	0		5	Gamma
	3			3			4	
	2	Digital Zoom Position (H)		2	Spot AE Position (X)	13	3	High Sensitivity mode (1: On, 0: Off)
	1			1				
	0			0			2	
	7	0		7	0		1	NR Level
	6	0		6	0		0	
	5	0		5	0		7	0
3	4	0	9	4	0		6	
	3			3			5	Chroma Suppress
	2	Digital Zoom Position (L)		2	Spot AE Position (Y)	14	4	
	1			1			3	
	0			0			2	Gain Limit
	7	0		7	0		1	
	6	0		6	0		0	
	5	0		5	0		7	1 Terminator (FFh)
4	4	0	10	4	0		6	1
-	3			3	0		5	1
	2	AF Activation Time (H)		2	MD (1: On, 0: Off)	15	4	1
	1			1	0		3	1
	0			0	E-Flip (1: On, 0: Off)		2	1
	7	0					1	1
	6	0					0	1
	5	0						
5	4	0						
5	3							
	2	AE Activation Time (I)						
	1	AF Activation Time (L)						
	0							48

# Extended Function2 Query Command .....Command Packet 8x 09 7E 7E 04 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	Destination Address		6	0		6	0
	5	Destination Address		5	0		5	0
0	4			4	0		4	0
0	3		6	3	0	11	3	0
	2			2	0		2	0
	1	Source Address		1	Compensation level		1	0
	0			0	0: Low 1: Mid 2: High		0	0
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
	4	1		4	0		4	0
1	3	0	7	3	0	12	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0		0	Defog 0: Off 1: On		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
	4	0		4	0		4	0
2	3	0	8	3	0	13	3	0
	2	0		2	0		2	0
	1	VE		1	Defog Level		1	0
	0	0: Off 2: VE On		0	0: mid 1: low 2: mid 3: high		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
	4	0		4	0		4	0
3	3	0	9	3	0	14	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0		0	0		0	0
	7	0		7	0		7	1 Terminator (FFh)
ŀ	6	0		6	0		6	1
	5	0		5	0		5	1
	4	0		4	0		4	1
4	3	0	10	3	0	15	3	1
	2	Display brightness level setting		2	0		2	1
	1	0: Dark to 6: Bright		1	0		1	1
	0			0	0		0	1
	7	0						
	6	0						
	5	0						
	4	0						
5	3	0						
	2	0						
	1	Brightness compensation selection						
	0	0: Very dark 1: Dark 2: Standard						
	1	3. Bright						

3: Bright

# Extended Function3 Query Command .....Command Packet 8x 09 7E 7E 05 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments	
	7			7	0		7	0	
	6	Destination Address		6		]	6		
	5	5	5			5			
0		6	4		11	4			
0	3		0	3	Reserved		3	Reserved	
	2	Source Address		2			2		
	1	Source Address		1			1		
	0			0			0		
	7	0 Completion Message (50h)		7	0		7	0	
	6	1		6			6		
	5	0		5			5		
1	4	1	7	4		12	4		
1	3	0		3	Reserved		3	Reserved	
	2	0		2			2		
	1	0		1			1		
	0	0		0			0		
	7	0		7	0	41	7	0	
	6	0		6			6		
	5	0		5			5		
2	4	0	8	4	_	13	4		
	3			3	Reserved		3	Reserved	
	2	Color Hue		2			2		
	1	(0h(- 14 degrees) to Eh(+ 14 degrees))					1		
	0			0			0		
	7	0		7	0		7	0	
	6		9	9	6			6	
	5				9	5		5	
	4							4	
3	3	Reserved				3	Reserved	14	3
	2				2			2	
	1					1			1
	0			0			0		
	7	0		7	0		7	1 Terminator (FFh)	
	6			6			6	1	
	5			5			5	1	
4	4		10	4		15	4 3	1 1	
	3	Reserved		3	Reserved		2		
	2			2				1	
	1			1			1	1	
	0			0			0	1	
	7	0							
	6								
	5								
5	4								
5	3	Reserved							
	2								
	1								
	0								

# **VISCA Command Setting Values**

## Exposure control (1/2)

		59.94/29.97 mode	50/25 mode
Shutter Speed	15	1/10000	1/10000
	14	1/6000	1/6000
	13	1/4000	1/3500
	12	1/3000	1/2500
	11	1/2000	1/1750
	10	1/1500	1/1250
	0F	1/1000	1/1000
	0E	1/725	1/600
	0D	1/500	1/425
	0C	1/350	1/300
	0B	1/250	1/215
	0A	1/180	1/150
	09	1/125	1/120
	08	1/100	1/100
	07	1/90	1/75
	06	1/60	1/50
	05	1/30	1/25
	04	1/15	1/12
	03	1/8	1/6
	02	1/4	1/3
	01	1/2	1/2
	00	1/1	1/1

T ·		
Iris	11	F1.8
	10	F2
	0F	F2.4
	0E	F2.8
	0D	F3.4
	0C	F4
	0B	F4.8
	0A	F5.6
	09	F6.8
	08	F8
	07	F9.6
	06	F11
	05	F14
	00	CLOSE

10	45 dB
0F	42 dB
0E	39 dB
0D	36 dB
0C	33 dB
0B	30 dB
0A	27 dB
09	24 dB
08	21 dB
07	18 dB
06	15 dB
05	12 dB
04	9 dB
03	6 dB
02	3 dB
01	0 dB

0D to 10 can be set only when the high-sensitivity mode is ON.

Gain

		High Sensitivity mode		
		Off	On	
Gain Limit	С	33 dB	45 dB	
	В	30 dB	42 dB	
	А	27 dB	39 dB	
	9	24 dB	36 dB	
	8	21 dB	33 dB	
	7	18 dB	30 dB	
	6	15 dB	27 dB	
	5	12 dB	24 dB	
	4	9 dB	21 dB	

## Exposure control (2/2)

		Iris	Gain
Bright	20	F1.8	45 dB
	1F	F1.8	42 dB
	1E	F1.8	39 dB
	1D	F1.8	36 dB
	1C	F1.8	33 dB
	1B	F1.8	30 dB
	1A	F1.8	27 dB
	19	F1.8	24 dB
	18	F1.8	21 dB
	17	F1.8	18 dB
	16	F1.8	15 dB
	15	F1.8	12 dB
	14	F1.8	9 dB
	13	F1.8	6 dB
	12	F1.8	3 dB
	11	F1.8	0 dB
	10	F2	0 dB
	0F	F2.4	0 dB
	0E	F2.8	0 dB
	0D	F3.4	0 dB
	0C	F4	0 dB
	0B	F4.8	0 dB
	0A	F5.6	0 dB
	09	F6.8	0 dB
	08	F8	0 dB
	07	F9.6	0 dB
	06	F11	0 dB
	05	F14	0 dB
	00	CLOSE	0 dB

1D to 20 can be set only when the high-sensitivity mode is ON.

ſ	r	1	
Exposure Comp.	0E	+7	+10.5 dB
	0D	+6	+9 dB
	0C	+5	+7.5 dB
	0B	+4	+6 dB
	0A	+3	+4.5 dB
	09	+2	+3 dB
	08	+1	+1.5 dB
	07	0	0 dB
	06	-1	-1.5 dB
	05	-2	-3 dB
	04	-3	-4.5 dB
	03	-4	-6 dB
	02	-5	-7.5 dB
	01	-6	-9 dB
	00	-7	-10.5 dB

# Zoom Ratio and Zoom Position (for reference)

Optical Zoom Ratio	Optical Zoom Position Data
1×	0000
2×	1970
3×	249C
4×	2B5F
5×	3020
6×	33C4
7×	36B7
8×	392F
9×	3B4D
10×	3D1E
11×	3EAD
12×	4000

## Digital Zoom Combine mode

Digital Zoom Ratio	Digital Zoom Position Data
1×	4000
2×	6000
3×	6A80
4×	7000
5×	7300
6×	7540
7×	76C0
8×	7800
9×	78C0
10×	7980
11×	7A00
12×	7AC0

#### **Digital Zoom Separate mode**

Digital Zoom Ratio	Digital Zoom Position Data
1×	00
2×	80
3×	AA
4×	C0
5×	CC
6×	D5
7×	DB
8×	E0
9×	E3
10×	E6
11×	E8
12×	EB

### Lens control

	0000 to 4000 to 7AC0				
Zoom Position	Wide end Optical Digital				
	Tele end Tele end				
Focus Position	1000 to F000				
	Far end Near end				
	1000: Over Inf				
	2000: 10 m				
	3000: 5 m				
	4000: 3.3 m				
	5000: 2.5 m				
	6000: 2 m As the distance on the left				
Focus Near	7000: 1.7 m will differ due to temperature				
Limit	8000: 1.5 m characteristics, etc., use as				
	9000: 1 m approximate values. *The lower 1 byte is fixed at 00.				
	A000: 50 cm				
	B000: 30 cm				
	(initial setting)				
	C000: 15 cm				
	D000: 6 cm				
	E000: 1 cm				

## Wide/Tele Limit Setting

Wide/Tele Limit	Wide Li	imit	Tele Liı	mit
	Zoom	Zoom	Zoom	Zoom
Setting Value	Position	Ratio	Position	Ratio
00	0000	1.00	4000	12.00
10	01EE	1.05	3E11	10.59
20	03DD	1.09	3C22	9.44
30	05CC	1.15	3A33	8.46
40	07BB	1.20	3844	7.61
50	09A9	1.26	3656	6.86
60	0B98	1.33	3467	6.20
70	0D87	1.40	3278	5.62
80	0F76	1.48	3089	5.10
90	1165	1.56	2E9A	4.65
A0	1353	1.65	2CAC	4.24
B0	1542	1.75	2ABD	3.89
C0	1731	1.86	28CE	3.57
D0	1920	1.98	26DF	3.29
E0	1B0F	2.11	24F0	3.04
F0	1CFD	2.26	2302	2.82
FF	1ECD	2.41	2132	2.63

# Temperature Reading Conversion Value (Reference Value)

Reading Value pq (hex)	Temperature Conversion Value (°C)
FB	-8 to -2
00	-3 to +3
0A	7 to 13
14	17 to 23
1E	27 to 33
28	37 to 43
32	47 to 53
3C	57 to 63

### **Register Setting**

The register settings are enabled when the power is turned off and then back on again. After turning the power back on again, verify that the mode settings have been changed.

	Register No.	Value	
VISCA	00	00	9600 bps
Baud Rate	00		9000 008
Daud Kale		(Iinitial Setting) 01	19200 bps
		01	38400 bps
		03	57600 bps
		03	115200 bps
Digital	60	00	YUV
Output	00	(Iinitial Setting)	101
Output		01	RGB
Monitoring	72	1D	System: QFHD (3840 × 2160)
Mode		(Iinitial Setting)	29.97p
mode		(initial octains)	Output: 3840 × 2160 29.97p
			$1920 \times 1080 59.94 p (2-2)$
			When electronic pan/tilt is
			ON.
		1.E	
		1E	System: QFHD (3840 × 2160)
			25p
			Output: 3840 × 2160 25p
			1920 × 1080 50p (2-2)
			When electronic pan/tilt is
			ON.
		13	System: FHD (1920 × 1080)
			59.94p
			Output: 1920 × 1080 59.94p
		14	System: FHD (1920 × 1080)
			50p
			Output: 1920 × 1080 50p
		01	System: FHD (1920 × 1080)
			59.94i
			Output: 1920 × 1080 59.94i
		04	System: FHD (1920 × 1080)
			50i
			Output: 1920 × 1080 50i
		06	System: FHD (1920 × 1080)
			29.97p
			Output: 1920 × 1080 59.94p
			(2-2)
		08	System: FHD (1920 × 1080)
			25p
			Output: 1920 × 1080 50p (2-2)
		09	System: HD (1280 × 720)
			59.94p
			Output: 1280 × 720 59.94p
		0C	System: HD (1280 × 720) 50p
			Output: 1280 × 720 50p
		0E	System: HD (1280 × 720)
			29.97p
			Output: 1280 × 720 59.94p (2-2)
		11	System: HD (1280 × 720) 25p
			Output: 1280 × 720 50p (2-2)

The frame rate of system in the monitoring mode is the screen update interval. (2-2) in Output indicates that the same image is output two times.

	Register No.	Value	
Low Delay	75	00	Normal Mode
Mode		01	Low Delay Mode
Zoom Limit	50	00-FF	Wide Limit
		(Iinitial Setting: 00)	(0: Disabled)
	51	00-FF	Tele Limit
		(Iinitial Setting: 00)	(0: Disabled)
D-Zoom Max	52	00-EB	Max. digital
		(Iinitial Setting: EB)	zoom ratio =
			256 ÷ (256-Value)
"StableZoom"	53	00	Off
		(Iinitial Setting: 00)	
		01	On
FocusTrace	54	00	Off
@ZoomDirect		01	On
		(Iinitial Setting: 01)	
FocusOffset	55	00-FF	00: None to
@DomeCover		(Iinitial Setting: 00)	FF: Max.
Extended	5F	00	0FF
Mode		bit: 0 Exposure com	pensation
		Extended 256 levels	On/Off
		bit: 1 Aperture Exte	nded 256 levels
		On/Off	
		bit: 2 Color Gain/H	ue Extended 256
		levels On/Off	
		bit: 3 Auto ICR Off	$\rightarrow$ On setting
		enable On/Off	-
		*For all of bit, 1 is to	activate, 0 is Off

When both low delay mode and stable zoom are On, the low delay mode takes precedence.

#### Others

00	to	FF
	to	
		FF
00	to	0F
00	to	0F
00	to	FF
00	to	FF
00	to	0F
01	to	30
00	to	FF
00	to	FF
00	to	FF
00	to	10
00	to	08
00	to	03
00	to	0E
00	to	0E
00	to	7F
00	to	7F
	D0       D0       D0       D0       D0       D0       D1       D0       D0	10         10           00         to           00         to

<sup>1)</sup> Unit: One second

### USB commands for firmware update

#### Basic specifications of commands and response

• Communication is performed in units of packets.

- The packet consists of a header (32 bytes) and body (from 0 byte).
- Two types of packets in a command and response are defined as described below.
  - Command Data transfer of a host to this unit
  - Response Data transfer of this unit to a host
  - One response packet is necessarily returned to one command packet.
  - \* However, there is no response in a specific command.
- Byte array is based on a little-endian format.
- Description of notation
- Notation of type
- uint: Unsigned integer (Does not depend on the data length.)

Binary: Binary data string

Packet structure

The packet consists of a fixed-length (32-byte) header and size-variable body.

The maximum packet size is prescribed for each command or during communication parameter setting.

Data array	Size [Byte]	Туре
Packet{		
Packet Header	32	Packet Header
Body	n	Binary
}		

• Packet Header (Common in both a command and response)

Data array	Size [Byte]	Туре
Packet Header{		
BodySize	4	uint
Protocol Version	2	uint
Command ID	2	uint
Response ID	2	uint
Sequence No.	2	uint
reserved	4	uint
reserved	4	uint
reserved	4	uint
reserved	8	uint
}		

# Meaning

### **Body Size**

This is the size of a body following a packet header. (The size of a packet header is not contained.)

### **Protocol Version**

This is the version of a communication protocol. Fixed to 0x0100.

(The host sets the protocol version contained in firmware data.)

#### Command ID

Command packet: Sets the command to be executed. The same value as the Response packet: corresponding command packet is set. **Response ID** Command packet: Fixed to 0x0000. Response packet: ID indicating the processing result of the corresponding command For more details, refer to the specifications for each command. (See pages 58 to 62.) Sequence No. Command packet: Sequence number unique in all commands Returned to 1 when an overflow occurs in the range of 1 to 65536. Response packet: Returns the sequence number of the corresponding command as it is. An error does not especially occur even when the value of a sequence number is skipped.

#### Body

Data used as each command and response parameter is stored.

The body varies depending on each command and response.

## ID list

Command ID	Definition of ID	Outline description
/*Initial communicatio	n*/	
0x0001	CMD_INIT	Initializes communication.
/*Judgment of rush cor	nditions*/	
0x0010	CMD_CHK_GUARD	Starts the judgment of rush conditions.
/*Inquiry of firmware v	version*/	
0x0020	CMD_QUERY_VERSION	Inquires the version of firmware.
/*Start mode switching	request*/	
0x0030	CMD_SWITCH_MODE	Executes the switching to a firmware update mode.
/*Firmware rewrite*/		
0x0040	CMD_WRITE_FIRM	Transfers firmware data and writes it.
/*Completion check no	tification of rewrite processing*/	
0x0100	CMD_COMPLETE	Notifies the completion check of firmware update.
/*Acquisition of firmwa	are update processing status in this unit*/	
0x0200	CMD_GET_STATE	Acquires the firmware update processing status.

Posnonso ID	Definition of ID	Outline description (The detailed meaning varies depending on
Response ID	(STAT_ is also the same.)	each command.)
/*Normal system*/		
0x0001	ERR_OK	Normal termination
0x0002	ERR_BUSY	Processing in progress
/*Communication prof	tocol error*/	
0x0100	ERR_PROV	Difference in protocol version
0x0101	ERR_SEQUENCE	Sequence error. This is not a state in which a command can be received.
0x0102	ERR_BIG	A packet is too large. (A receive buffer is insufficient.)
0x0103	ERR_INVALID_PARAM	A parameter is illegal.
/*0x1xxx: Processing et	rror in this unit*/	
0x1xxx	ERR_INTERNAL	Internal processing error in this unit

Response ID	Definition of ID	Outline description (The detailed meaning varies depending on each command.)
/*Normal system*/		
0x0001	STAT_OK	
0x0002	STAT_BUSY	
/*Status of rush condition	ons*/	
0x0140	STAT_INVALID_MODEL	A model differs.
0x0141	STAT_INVALID_REGION	Destination differs.
/*Firmware data error*/		
0x0040	STAT_INVALID_DATA	The received firmware data is illegal (damaged).
		(The data is falsified and cannot be detected by CRC of a package file.)

# A processing error in this unit is notified to a ResponseID field as an error.

CurStatus ID	Definition of ID	Outline description
0x0100	CURSTAT_PRE_INIT	Before CMD_INIT reception
0x0200	CURSTAT_PRE_SWITCHMODE	After CMD_SWITCHMODE reception

## Command specifications

Command	Desc	cription				
CMD_GET_STATE	• Out					
	Thi	s command acquires the firmware update	processing status in th	is unit.		
		his command can be accepted at any time v				
		Command parameter				
	Nor					
		ponse (ID/Parameter)				
		<b>R_OK</b>				
		Initialization succeeded. The subsequent r	narimum nachat aiza a	nd minimum tim	a out are turned to a parameter	
		Parameter →	naximum packet size a		le-out are turned to a parameter.	
		Parameter data arrangement	Size [Byte]	Туре		
		OK Parameter{				
		currentState ID	2	uint		
		}				
		<ul> <li>Meaning</li> </ul>				
		currentState ID				
		This is the set state at the point of tim		was received.		
		Refer to the ID list of each STAT ID.				
			•		ssues a CMD_INIT command	
					nmand cannot be returned by INIT)	
			n when PC application	issues a CMD_S	WITCH_MODE command	
		R_PROV				
		This cannot be used for the communication	on protocol version set	to a packet heade	r.	
		No parameter				
	<ul> <li>Ren</li> </ul>	narks				
CMD_INIT	• Out	tline				
	Thi	s command initializes communication and	l transfers the required	l parameter.		
	Thi	s unit returns the internal state to the initi	al state by receiving the	e parameter.		
	The	ere is a state in which the parameter canno	t be received.			
	<ul> <li>Cor</li> </ul>	nmand parameter				
	Nor	-				
		lle				
	• Res	ponse (ID / Parameter)				
	• Res	ponse (ID / Parameter) <b>R_OK</b>	naximum packet size a	und minimum tim	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r	naximum packet size a	und minimum tim	ne-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter →			e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement	naximum packet size a Size [Byte]	und minimum tim <b>Type</b>	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>S_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{	Size [Byte]	Туре	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>B_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize	Size [Byte]	<b>Type</b> uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize	<b>Size [Byte]</b> 4 4 4	Type uint uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	Size [Byte] 4 4 4 4 4	Type uint uint uint	ne-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	<b>Size [Byte]</b> 4 4 4 4 4 4 4	Type uint uint uint uint	ne-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	Size [Byte] 4 4 4 4 4	Type uint uint uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	<b>Size [Byte]</b> 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse }	<b>Size [Byte]</b> 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning	<b>Size [Byte]</b> 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.	
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize	Size [Byte]	Type uint uint uint uint uint		
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by	Size [Byte] 4 4 4 4 4 4 4 4 5 5 5 5 5 5 5 5 5 5 5	Type uint uint uint uint uint		
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize	Size [Byte] 4 4 4 4 4 4 4 4 5 5 5 5 5 5 5 5 5 5 5	Type uint uint uint uint uint		
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by	Size [Byte] 4 4 4 4 4 4 4 4 5 5 5 5 5 5 5 5 5 5 5	Type uint uint uint uint uint		
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter →  Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeResponse }  Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE	Size [Byte] 4 4 4 4 4 4 te] of a command pack command	Type uint uint uint uint	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter →  Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeResponse }  Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize	Size [Byte] 4 4 4 4 4 4 te] of a command pack command	Type uint uint uint uint	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe	Type uint uint uint uint uint cet after initialization	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → <b>Parameter data arrangement</b> OK Parameter{ OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe	Type uint uint uint uint uint cet after initialization	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the maximum packet size [by minTimeOut This is the minimum timeout time [n succeeded.	Size [Byte] 4 4 4 4 4 te] of a command pack command te] of a response packe nsec] common to each	Type uint uint uint uint uint et after initialization a command after o	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>3_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [n	Size [Byte] 4 4 4 4 4 te] of a command pack command te] of a response packe nsec] common to each	Type uint uint uint uint uint et after initialization a command after o	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>R_OK</b> Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded. The host must time out using a value intervalBeforeCommand	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe nsec] common to each e of more than the min	Type uint uint uint uint uint et after initialization a command after o imum timeout tir	ion has succeeded.	
	• Res	<pre>ponse (ID / Parameter) </pre> <pre>A_OK Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{     maxCmdPacketSize     minTimeOut     intervalBeforeCommand     intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded. The host must time out using a value intervalBeforeCommand This is the min time [msec] required</pre>	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe nsec] common to each e of more than the min	Type uint uint uint uint uint et after initialization a command after o imum timeout tir	ion has succeeded.	
	• Res	ponse (ID / Parameter) <b>A_OK</b> Initialization succeeded. The subsequent reparameter → <b>Parameter data arrangement</b> OK Parameter{ MaxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the maximum packet size [by minTimeOut This is the maximum packet size [by not including a CMD_GET_STATE maxResPacketSize This is the minimum timeout time [resucceeded. The host must time out using a value intervalBeforeCommand This is the minimum timeout time [resucceeded. The host must time out using a value intervalBeforeCommand This is the minimum function [resucceeded. The host must time out using a value intervalBeforeCommand This is the minimum function [resucceeded. The host must time out using a value intervalBeforeCommand This is the minimum function [resucceeded. The host must time out using a value intervalBeforeCommand This is the minimum function [resucceeded. The host must time [msec] required intervalBeforeResponse	Size [Byte] 4 4 4 4 4 4 4 te] of a command pack command te] of a response packet nsec] common to each cof more than the min from when the host response to the sector of th	Type uint uint uint uint uint uint et after initialization a command after of imum timeout tir eccives a response	ion has succeeded. on has succeeded. communication initialization has ne. until it issues the next command.	
	• Res	<pre>ponse (ID / Parameter) </pre> <pre>A_OK Initialization succeeded. The subsequent r Parameter → Parameter data arrangement OK Parameter{     maxCmdPacketSize     minTimeOut     intervalBeforeCommand     intervalBeforeResponse } • Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded. The host must time out using a value intervalBeforeCommand This is the min time [msec] required</pre>	Size [Byte] 4 4 4 4 4 4 4 4 4 4 5 command pack command pack common to each common to each common the host re- from when the host is	Type uint uint uint uint uint uint et after initialization a command after of imum timeout tir eccives a response	ion has succeeded. on has succeeded. communication initialization has ne. until it issues the next command.	

Command	Description						
CMD_INIT	ERR_PROV						
				1			
	This cannot be used for the communication protocol version set to a packet header.						
	No parameter						
	ERR_SEQUENCE						
	Communication sequence error. No	parameter.					
	This is a state in which a CMD_INI	-	ceived.				
	Remarks						
CMD CHK CUARD	Outline						
CMD_CHK_GUARD							
	This command starts the confirmation	processing of rush condit	tions.				
	Command parameter			_			
	Parameter data arrangement	Size [Byte]	Туре				
	CHK_GUARD Parameter{			1			
	dataNo	4	uint	7			
	remainSize	4	uint	-			
	firmData	dataSize		-			
		uataSize	Binary	-			
	<u>}</u>						
	<ul> <li>Meaning</li> </ul>						
	dataNo.						
		. 1 . 1	1. 0	1 1 "o"			
	This is the number of times by whi			h conditions. "0" is not used.			
	Increment this from 1 irrespective	of the existence of firmI	Data.				
	remainSize						
	This is the size of firmware data th	at has not been transmit	ted yet. (The data si	ze becomes zero during final			
	transfer.)			C C			
	This gives compatibility with the V	VDITE FIRM command	described later				
		V KI I E_FIKIVI Command	i described later.				
	firmData						
			To confirm rush conditions, the top of firmware data (the data division of "FDAT" chunk) is split for transfer. The				
		p of firmware data (the c	lata division of "FD	fill enality is split for transfer. The			
	To confirm rush conditions, the to size of data to be transferred is spe						
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65.						
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter)	cified by windowSize. Op	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary	cified by windowSize. Of	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter)	cified by windowSize. Of	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary	cified by windowSize. Of	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b>	cified by windowSize. Of	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize	cified by windowSize. Op depending on response I Size [Byte] 4	peration is complete D Type uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus	cified by windowSize. Op depending on response I Size [Byte]	peration is complete				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID	cified by windowSize. Op depending on response I Size [Byte] 4	peration is complete D Type uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } {	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { . Meaning	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } {	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { . Meaning	cified by windowSize. Op depending on response I Size [Byte] 4 4 4 2 2	peration is complete D Type uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that the	cified by windowSize. Op depending on response I Size [Byte] 4 4 4 2 2	peration is complete (D <u>Type</u> uint uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { . Meaning windowSize This is the size of firmData that th A packet (including firmData) of h	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 nis unit can receive. ess than windowSize can	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 nis unit can receive. ess than windowSize can	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus	cified by windowSize. Optimized by windowSize. Optimized by the second state of the s	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize	cified by windowSize. Optimized by windowSize. Optimized by the second state of the s	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus	cified by windowSize. Optimized by windowSize. Optimized by the second state of the s	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of L It is necessary to satisfy packetSize numStatus This is the number of status IDs for	cified by windowSize. Operation of the second state of the second	peration is complete D Type uint uint uint uint	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of h It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush conditi	cified by windowSize. Optimized by windowSize. Optimized by the set of the s	peration is complete (D Type uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I- It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK	cified by windowSize. Opdepending on response I Size [Byte] 4 4 4 2 2 bis unit can receive. ess than windowSize can $\ge 32$ [byte] header + willowing numStatus. tions Conditions are satisfied.	peration is complete (D Type uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I. It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_BUSY	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 is unit can receive. ess than windowSize can $\geq 32$ [byte] header + willowing numStatus. tions Conditions are satisfied. Processing in progress	peration is complete (D Type uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 bis unit can receive. ess than windowSize can $\geq 32$ [byte] header + w llowing numStatus. tions Conditions are satisfied. Processing in progress A model differs.	peration is complete (D Type uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of IL It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush conditt STAT_OK STAT_BUSY STAT_INVALID_MODEL	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 is unit can receive. ess than windowSize can $\geq 32$ [byte] header + willowing numStatus. tions Conditions are satisfied. Processing in progress	peration is complete (D Type uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_REGION	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 bis unit can receive. ess than windowSize can $\geq 32$ [byte] header + w llowing numStatus. tions Conditions are satisfied. Processing in progress A model differs.	peration is complete (D <b>Type</b> uint uint uint be received. indowSize + 8 (para	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of L It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 2 4 2 2 4 2 2 4 2 2 4 2 4 2 2 4 2 2 4 2 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 5 2 5 5 5 5 5 5 5 5 5 5 5 5 5	ed.	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary <b>Parameter data arrangement</b> Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of L It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 2 4 2 2 4 2 2 4 2 2 4 2 4 2 2 4 2 2 4 2 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 2 5 5 2 5 5 5 5 5 5 5 5 5 5 5 5 5	ed.	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of L It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	ed.	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of l- It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush conditt STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally.	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	ed.	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of L It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	ed.	ed when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of l- It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush conditt STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally.	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 bis unit can receive. ess than windowSize can $\geq 32$ [byte] header + w. llowing numStatus. tions Conditions are satisfied. Processing in progress A model differs. Destination differs. Firmware data is damage y set as Status ID at the t	ed.	aumeters other than firmData).			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 64 and 65. Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for ( i = 0; i < numStatus; i++){ Status ID } { Meaning windowSize This is the size of firmData that th A packet (including firmData) of I. It is necessary to satisfy packetSize numStatus This is the number of status IDs fo Status ID Confirmation result of rush conditt STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally. ERR_PROV	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 bis unit can receive. ess than windowSize can $\geq 32$ [byte] header + w. llowing numStatus. tions Conditions are satisfied. Processing in progress A model differs. Destination differs. Firmware data is damage y set as Status ID at the t	ed.	aumeters other than firmData).			

Command	Description				
CMD_CHK_GUARD	ERR_SEQUENCE				
	Communication sequence error. No parar	neter.			
	Communication sequence error. No parameter. This cannot be received before communication is initialized.				
	ERR_BIG	actori is initianized.			
	Packet size is too large.				
	ERR_INVALID_PARAM				
	dataNo is invalid. (A value is skipped.) da				
	Errors other than described above are process	sing errors in this unit.			
CMD_QUERY_VERSION	Outline				
	This command inquires the version of new ar	nd old firmware.			
	Command parameter				
	None				
	<ul> <li>Response (ID/Parameter)</li> </ul>				
	ERR_OK				
	Normal termination. The version of new a	and old firmware is ret	urned using a param	ieter.	
	Parameter +				
	Parameter data arrangement	Size [Byte]	Туре	]	
	OK Parameter{		.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		
	oldFirmMinorVersion	2	uint	1	
	oldFirmMajorVersion	2	uint	1	
	newFirmMinorVersion	2	uint	1	
	newFirmMajorVersion	2	uint		
	}		unit	1	
	ــــــــــــــــــــــــــــــــــــــ	<u>                                     </u>		1	
	<ul> <li>Meaning</li> </ul>				
	oldFirmMinorVersion				
	oldFirmMajorVersion				
	Minor and major version numbers o	f old firmware			
	newFirmMinorVersion				
	newFirmMajorVersion				
	Minor and major version numbers o	f new firmware			
	Fixed to 0x0000 before rush condition		he version is not kno	own vat	
			he version is not kno	Jwii yet.	
	ERR_PROV				
	This cannot be used for the communication	on protocol version set	to a packet header.		
	No parameter				
	ERR_SEQUENCE				
	Communication sequence error. No parar				
	This cannot be accepted before communio	cation is initialized.			
	Errors other than described above are processin	ng errors in this unit.			
CMD_SWITCH_MODE	Outline				
	This command performs switching to a firmy	vare update mode.			
	Command parameter				
	None				
	Response (ID/Parameter)				
	ERR_OK				
	A firmware update mode switching command is received normally.				
	Parameter +		1-		
		Cinc (Dect. )	<b>T</b>	1	
	Parameter data arrangement	Size [Byte]	Туре	•	
	OK Parameter{		• •		
	• •	4	uint		
	reserved = 0	1		1	
	numStatus = 1	4	uint		
		1	uint uint	- - -	
	numStatus = 1	4		•	
	numStatus = 1 Status ID }	4			
	numStatus = 1 Status ID } • Meaning	4			
	numStatus = 1 Status ID } • Meaning numStatus	4 2	uint		
	numStatus = 1         Status ID         }         • Meaning         numStatus         This is the number of statuses follow	4 2	uint		
	numStatus = 1         Status ID         }         • Meaning         numStatus         This is the number of statuses follow         Status ID	4 2 ring numStatus. (Fixed	uint to 1.)		
	numStatus = 1         Status ID         }         • Meaning         numStatus         This is the number of statuses follow         Status ID	4 2	uint to 1.)		

Command	Description				
CMD_SWITCH_MODE	ERR_PROV				
CINE_0111011_MODE		cation protocol version	set to a nacket he	nder	
	This cannot be used for the communication protocol version set to a packet header.				
	No parameter				
	ERR_SEQUENCE				
	Communication sequence error. No pa			J	
	This cannot be accepted while the app	lication of the main set	is in operation an	d when rush conditions are not	
	established.				
	Errors other than described above are in-s	set errors.			
CMD_WRITE_FIRM	• Outline				
	This command rewrites firmware.				
	Command parameter			_	
	Parameter data arrangement	Size [Byte]	Туре	_	
	WRITE_FIRM Parameter{			_	
	dataNo	4	uint		
	remainSize	4	uint		
	firmData		Binary		
	}				
	<ul> <li>Meaning</li> </ul>				
	dataNo				
	This is the number of times by which	this command was in	sued to transfor fir	mware data "N" is not used	
	This is incremented every time firm			inware data. 6 is not used.	
	This is reset by initialization of com				
	remainSize	numcation.			
		h h		in harmon and haring Coal	
	This is the size of firmware data that	has not been transmitt	ed yet. (The data s	size becomes zero during final	
	transfer.)				
	firmData		c		
	Firmware data (the data division of "FDAT" chunk) is split for transfer.				
		FDA1 chunk) is spin	ior transier.		
	*See pages 64 and 65.	FDA1 chunk) is spin	ior transier.		
	*See pages 64 and 65. • Response (ID/Parameter)				
	*See pages 64 and 65.			_	
	*See pages 64 and 65. • Response (ID/Parameter)				
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de	epending on response I	D		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	epending on response I	D		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{	epending on response I Size [Byte]	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize	epending on response I Size [Byte]	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1	epending on response I Size [Byte] 4	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID }	epending on response I Size [Byte] 4	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning	epending on response I Size [Byte] 4	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize	spending on response I Size [Byte] 4 2	D Type		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize • Meaning windowSize This is the size of firmData that this	spending on response I Size [Byte] 4 2 unit can receive.	D Type uint		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can	D Type uint be received.		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can	D Type uint be received.	rameters other than firmData).	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can	D Type uint be received.	rameters other than firmData).	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can	D Type uint be received.	rameters other than firmData).	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les. It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	D uint be received. ndowSize + 8 (par		
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	D uint be received. ndowSize + 8 (par s terminated norm	nally.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_OK Firmwa STAT_NVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	D uint be received. ndowSize + 8 (par s terminated norm	nally.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	D uint be received. ndowSize + 8 (par s terminated norm	nally.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version	D uint be received. ndowSize + 8 (par s terminated norm	nally.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter.	D UINT UINT be received. IndowSize + 8 (particular) s terminated norm s terminated norm	nally. nder.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted while an update	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter.	D UINT UINT be received. IndowSize + 8 (particular) s terminated norm s terminated norm	nally. nder.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter ERR_BIG	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operation	D UINT UINT be received. IndowSize + 8 (particular) s terminated norm s terminated norm	nally. nder.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter ERR_BIG This could not be received because page	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operation cket size is too large.	D uint uint be received. indowSize + 8 (par s terminated norm s terminated norm	nally. nder.	
	*See pages 64 and 65. • Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter ERR_BIG	epending on response I Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operation cket size is too large.	D uint uint be received. indowSize + 8 (par s terminated norm s terminated norm	nally. nder.	

Command	Description
CMD_WRITE_FIRM	ERR_INVALID_PARAM
	dataNo is invalid. (A value is skipped.) dataSize is invalid.
	Errors other than described above are errors in this unit.
	• Remarks
CMD_COMPLETE	• Outline
	This command notifies to confirm that firmware rewrite completion notification was accepted.
	Command parameter
	None
	•No response
	This unit is automatically restarted when this command is received.

#### Issuing the CMD\_CHK\_GUARD and CMD\_WRITE\_FIRM commands

Packet Header (	Common	in both a	command and	d response)
-----------------	--------	-----------	-------------	-------------

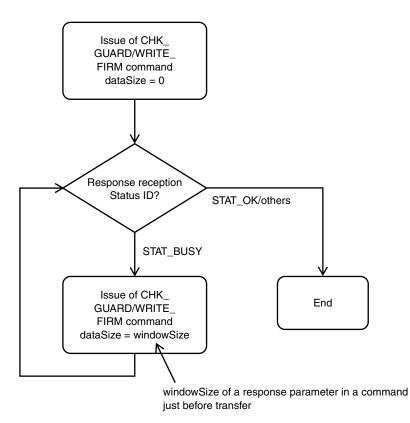
Data arrangement	Size [Byte]	Туре	
Packet Header{			
BodySize	4	uint	
Protocol Version	2	uint	
Command ID	2	uint	
Response ID	2	uint	
Sequence No.	2	uint	
reserved	4	uint	
reserved	4	uint	
reserved	4	uint	
reserved	8	uint	
}			

#### Command Parameter

Parameter data arrangement	Size [Byte]	Туре	
CHK_GUARD Parameter{			
dataNo	4	uint	
remainSize	2	uint	
firmData	dataSize	Binary	
}			

Parameter data arrangement	Size [Byte]	Туре
Response Parameter{		
windowSize	4	uint
numStatus	4	uint
for ( i = 0; i < numStatus; i++){		
Status ID	2	uint
}		
}		

Firmware data is transferred from the host to the unit using CHK GUARD and WRITE\_FIRM commands. For dataSize to be transferred, specify a value of less than windowSize set to the Response data that was issued just before transfer. When transmitting a command first, issue a command (with dataSize set to "0") without sending firmData and then issue a command for transferring data actually after confirming windowSize set to the Response data. Transmit data continuously until commands other than STAT\_BUSY are returned.

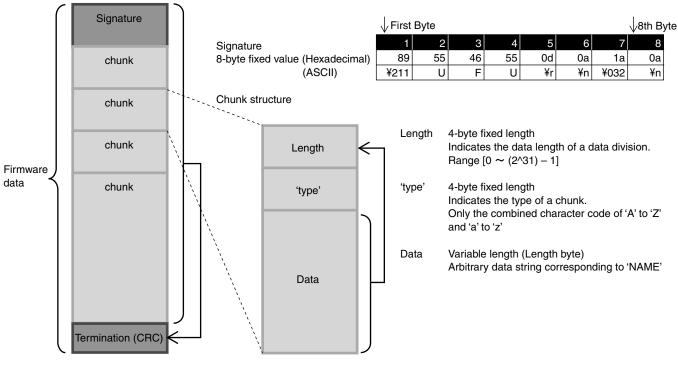


#### Discriminating the camera mode and updater mode

As described in the section of a UUD Firmware data structure, the USB PID, USB VID, and operating mode of equipment to be updated are described in the UDID chunk of firmware package data. The host to be updated confirms that USB PID and USB VID which acquired a USB descriptor from the unit are contained in the UDID chunk. By the ID operating mode, judge whether the unit is started in a camera mode or updater mode.

#### **Structure of UUD Firmware data**

- Signature is assigned to the top of data.
- One or more variable length chunk is continued after signature.
- A chunk containing a CRC32-calculated value is assigned to the termination of data.
- The byte order is based on a big-endian format. (MSB first)



#### Termination

Chunk indicating the termination data

The CRC-calculated value between the top of data (signature) and the chunk just before termination is stored.

For more details, see chunk list and detailed specifications. (pege 65)

## Chunk list and detailed specifications (Ver.1.0)

Description of type	
uint	Unsigned integer (Does not depend on the data length.)
Binary	Binary data string

Chunk type	Description			
DATV	Version of firmware data structure			
	<ul> <li>Limiting conditions</li> </ul>			
	This necessarily exists as a chunk at t	the top.		
	<ul> <li>Data arrangement</li> </ul>			
	Arrangement	Size [Byte]	Туре	Value
	DATV Chunk{			
	length	4	uint	0x0000004
	type	4	uint	'DATV'
	firmDataVersion	2	uint	
	reserved	2	uint	
	}			
PROV	reserved 0x0000 Communication protocol version of fi Limiting conditions This necessarily exists as the second Data arrangement	-		
	Arrangement	Size [Byte]	Туре	Value
	PROV Chunk{			
	length	4	uint	0x00000004
	type	4	uint	'PROV'
	firmProtocolVersion	2	uint	
	reserved = 0	2	uint	0x0000
	}			
	<ul> <li>Meaning firmProtocolVersion</li> </ul>			

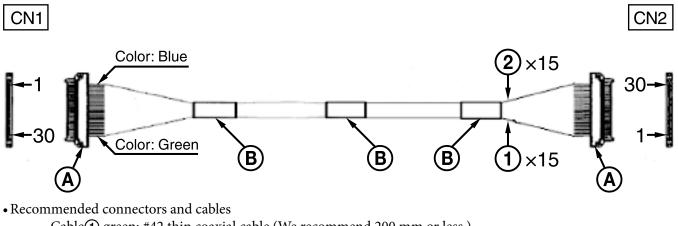
	Description				
UDID	List of PID and VID corresponding to this unit to be updated in firmware				
	Limiting conditions				
	This necessarily exists as a chunk.				
	<ul> <li>Data arrangement</li> </ul>				
	Arrangement	Size [Byte]	Туре	Value	
	UDID Chunk{	5120 [5910]	.,,,,,,		
	length	4	uint	4+id_count*	
	type	4	uint	'UDID'	
	id_count	4	uint		
	/* Descriptor ID List */	1	unit		
	for ( i=0; i < id_count; i++ ){				
	PID	2	ID		
	VID	2	ID		
	Operating mode	1	uint		
	reserved = 0	3	uint	0x000000	
			unit	0x00000	
	}				
FDAT	This is the corresponding PID. VID This is the corresponding VID. Operating mode This is information for identifying v during updater mode operation. ID during application operation of a ID during updater operation: Firmware data Limiting conditions This necessarily exists as a chunk. Data arrangement		ed during applicatio	on operation of a ma	
	Arrangement       FDAT Chunk{       length       type	4 4	uint uint	Value 'FDAT'	
	FDAT Chunk{ length	4	uint		
	FDAT Chunk{ length type	4 4	uint uint		
	FDAT Chunk{ length type Firmware data }	4 4	uint uint		
	FDAT Chunk{ length type Firmware data } • Meaning	4 4	uint uint		
DEND	FDAT Chunk{ length type Firmware data } • Meaning Firmware data	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignored	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is igno         • Data arrangement	4       4       length       red.	uint uint Binary	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignored	4 4 length	uint uint		
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is igno         • Data arrangement	4       4       length       red.	uint uint Binary	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignored         • Data arrangement         Arrangement	4       4       length       red.	uint uint Binary	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignored         • Data arrangement         DEND Chunk{	4           4           length           red.	uint uint Binary Type	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is igno         • Data arrangement <b>Arrangement</b> DEND Chunk{         length	4       4       length       red.	uint uint Binary Type uint	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignore         • Data arrangement <b>Arrangement</b> DEND Chunk{         length         type	4       4       length       i	uint uint Binary Type uint uint	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignore         • Data arrangement <b>Arrangement</b> DEND Chunk{         length         type	4       4       length       i	uint uint Binary Type uint uint	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignore         • Data arrangement <b>Arrangement</b> DEND Chunk{         length         type	4       4       length       i	uint uint Binary Type uint uint	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is ignor         • Data arrangement <b>Arrangement</b> DEND Chunk{         length         type         CRC         }	4       4       length       i	uint uint Binary Type uint uint	'FDAT'	
DEND	FDAT Chunk{         length         type         Firmware data         }         • Meaning         Firmware data         Chunk indicating the termination of data         • Limiting conditions         This necessarily exists as a chunk.         The data stream after this chunk is igno         • Data arrangement <b>Arrangement</b> DEND Chunk{         length         type         CRC         }         • Meaning	4       4       length       i	uint uint Binary Type uint uint uint uint	'FDAT' Value 'DEND'	

# Specifications

Imager Picture elements Lens	8930K p 12× Zoo F= 3.9 r (TE · Zoom Opti 1. 1. 0pti zo	om nm (WIDE) to 46.8 mm LE), F1.8 to F2.0 movement speed cal WIDE – Optical TELE 6 sec (Focus Tracking On) 3 sec (Focus Tracking Off) cal WIDE – Super resolution oom TELE
		9 sec
	-	cal WIDE – Digital zoom ELE
		8 sec
	· Focus	Movement time
	∞ to	Near 0.2 sec
Super resolution z		
	QFHD:	1.67× (Max. 20 times when combined with the optical zoom)
	FHD:	2.0× (Max. 24 times when combined with the optical zoom)
Digital zoom	12×	,
0		Max. 144× when combined with the optical zoom and Super resolution zoom
	FHD:	Max. 144× when combined with the optical zoom and Super resolution zoom
Angle of view (H)		
		. 70.7 degrees (wide end), rox. 6.2 degrees (tele end)
Min. working dist	ance	C C
		(wide end), 2100 mm e end)
Sync system	Internal	
Min. illumination (Typical value)	0.75 lx ( Hig 3.0 lx (1 Hig 0.1 lx (1 Sen: 0.38 lx (	

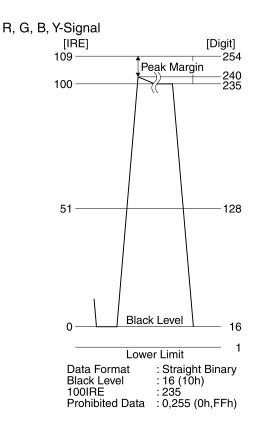
Recommended illumination 100 lx to 100,000 lx Back light compensation On/Off Electronic shutter speed 1/1 sec to 1/10000 sec (22 steps) Auto, ATW, Indoor, Outdoor, One White Balance Push WB, Manual WB, Outdoor Auto, Sodium Vapor Lamp (Fix/ Auto/Outdoor Auto) Gain Auto/Manual 0 to 33 dB Max. Gain Limit 9 to 33 dB Noise Reduction On/Off (level 5 to 1 / Off, 6 steps) Defog mode On/Off (Low, Mid, High) Color Enhancement On/Off Aperture control 16 steps Preset **16-POSITIONS** VISCA protocol (CMOS 3.1V) Camera control 9.6 kbps, 19.2 kbps, 38.4 kbps, 57.6 kbps, 115.2 kbps, Stop bit, 1 bit Video Output QFHD, FHD, HD: HDMI Storage temperature/Humidity -20 °C to +60 °C (-4 °F to +140 °F)/ 20% to 95% Absolute humidity: 36 g/m<sup>3</sup> Operating temperature/Humidity -5 °C to +60 °C (23 °F to +140 °F)/ 20% to 80% Absolute humidity: 36 g/m<sup>3</sup> Power requirements 6 V to 12 V DC Power consumption 2.9 W (during motor operation: 3.7 W) Mass Approx. 385 g (14 oz.) Dimensions  $60.0 \times 64 \times 105 \text{ mm}$  $(2^{3}/_{8} \times 2^{5}/_{8} \times 4^{1}/_{4} \text{ in.}) (w/h/d)$ 

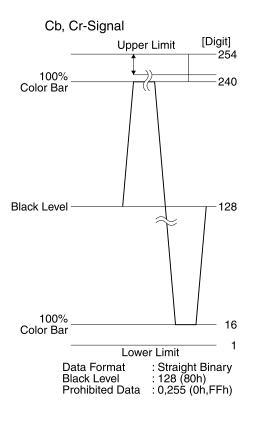
#### **Cable reference specifications (crossover)**



Cable green: #42 thin coaxial cable (We recommend 200 mm or less.) Cable blue: #42 thin coaxial cable (We recommend 200 mm or less.) Connector A: USL20-30S (KEL) Binding tape B

# DIGITAL Image Output Y, Cb, Cr 4:2:2 R, G, B 4:4:4 FORMAT Color coding complies with BT709.



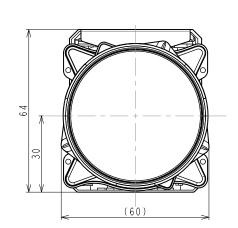


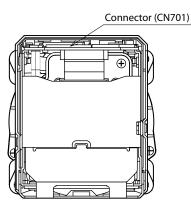
#### Dimensions

#### Front

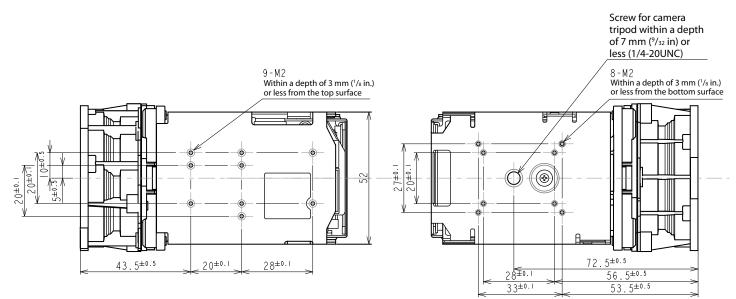
Тор

Back



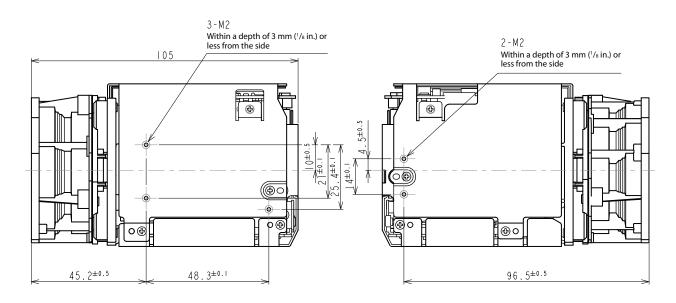


Bottom

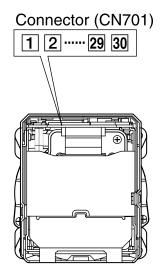


Left side

**Right side** 



Unit: mm (inches)



### CN701

KEL Co. USL00-30L-C

Pin No.	I/O	Name	Level
1	—	GND	
2	0	TMDS Clock –	
3	0	TMDS Clock +	
4	—	GND	
5	0	TMDS Data 0 –	
6	0	TMDS Data 0 +	
7	—	GND	
8	0	TMDS Data 1 –	
9	0	TMDS Data 1 +	
10	—	GND	
11	0	TMDS Data 2 –	
12	0	TMDS Data 2 +	
13	—	GND	
14	_	NC	
15	—	NC	
16	_	NC	
17	Ι	Hot Plug Detect	TMDS Out: 5V DC
			TMDS Stop: Open or GND
18	0	+ 5V Power	
19	Ι	USB_VBUS	USB communication active: 5 V DC
			USB communication
			inactive: Open or GND
20	—	GND	
21	I/O	USB_D -	
22	I/O	USB_D +	
23	—	GND	
24	Ι	VISCA_RxD	CMOS 3.1V
			(High: Min 2.3 [V],
			Low: Max 1.0 [V])
25	0	VISCA_TxD	CMOS 3.1V
			(High: Min 2.7 [V],
			Low: Max 0.4 [V])
26	Ι	RESET	Reset operation: Low (GND)
			Reset cancel: Open (High
			Impedance)
27	Ι	DC IN	6 to 12 V DC
28	Ι	DC IN	6 to 12 V DC
29	Ι	DC IN	6 to 12 V DC
30	Ι	DC IN	6 to 12 V DC

\* It is assumed that Pin No. 18 is used as the 5 V power supply of HDMI.
\* When you use the USB communication, connect VBUS of the USB host to Pin No. 19.

If you cannot prepare VBUS, connect Pin No. 18 to Pin No. 19.

#### Reset

This section describes about the camera reset specification.

#### • About the reset methods

There are two reset methods as follows. The reset operation is the same in both methods.

- Hardware reset

#### - Reset by Visca command

#### • Hardware reset

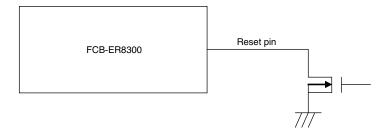
The reset operation/cancel can be controlled by sending the external signal to CN701 Pin26 (page 70).

Reset operation: Low (GND) Reset cancel: Open (High Impedance)

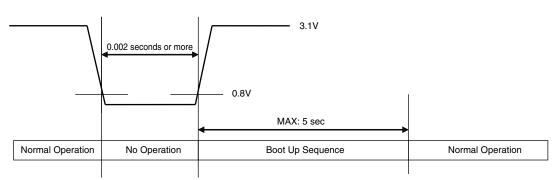
\*If there is a large resistance value between CN701 Pin26 and GND, the voltage is not completely decreased and the reset operation may not be performed. Please give consideration to reducing the resistance value. (100  $\Omega$  or less is recommended.)

#### - Example of reset circuit

Please note that we do not assume any responsibility for any loss or damage of your hardware arising from misuse or inappropriate use of the reset circuit example described below.

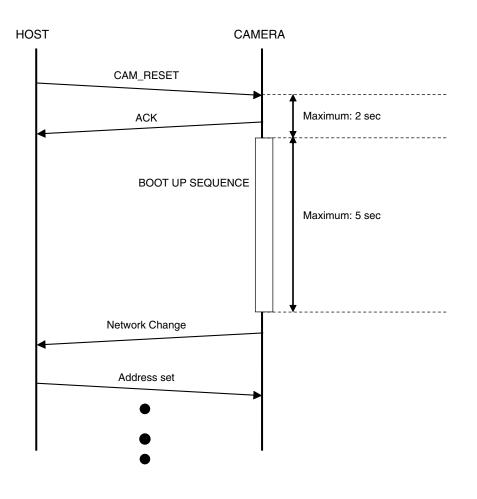


#### - Reset timing chart



## • Reset by Visca command

The time required from the end of camera reset to the issue of Network Change is as shown below.



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Please read the contents of description below at least once.

[linux-kernel] [busybox] [dosfstools] [e2fsprogs] [glibc] [hostname] [iptables] [procps] [util-linux-ng]

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Written by: Philip Hazel Email local part: ph10 Email domain: cam.ac.uk

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